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# Computer Graphics

## - Clipping -

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# Motivation

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- **Clipping**

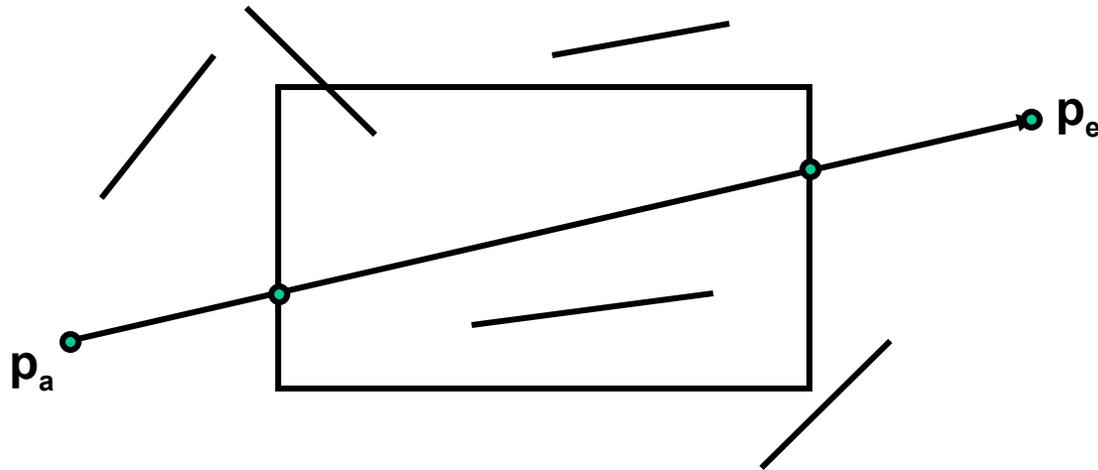
- Happens after transformation from 3D to 2D
- Many primitives will fall (partially) outside of display window
  - E.g. if standing inside a building
- Eliminates non-visible geometry early in the pipeline
- Must cut off parts outside the window
  - Cannot draw outside of window (e.g. plotter)
  - Outside geometry might not be representable (e.g. in fixed point)
- Must maintain information properly
  - Drawing the clipped geometry should give the correct results
  - Type of geometry might change
    - Cutting off a vertex of a triangle produces a quadrilateral
    - Might need to be split into triangle again
  - Polygons must remain closed after clipping

# Line clipping

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- **Definition Clipping:**

- Cut off parts of objects, which lie outside/inside of a defined region.
- Often: Clipping against a viewport (2D) or a canonical view-volume (3D)

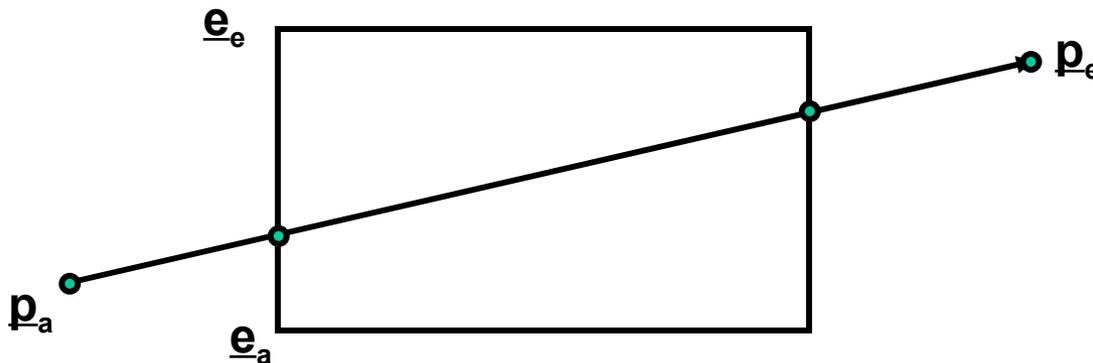


# Brute-force method

- **Brute-Force line clipping at the viewport**
  - If both points  $\underline{p}_a$  and  $\underline{p}_e$  are inside,
    - Accept the whole line
  - Otherwise, clip the line at each edge

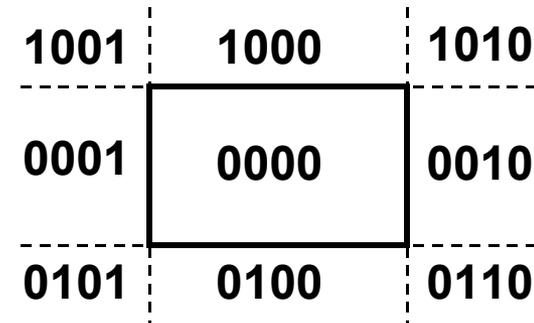
$$\underline{p} = \underline{p}_a + t_{line}(\underline{p}_e - \underline{p}_a) = \underline{e}_a + t_{edge}(\underline{e}_e - \underline{e}_a)$$

- Intersection point, if  $0 \leq t_{line}, t_{edge} \leq 1$
- Pick up suitable end points from the intersection points for the line



# Cohen-Sutherland ('74)

- **Advantage: divide and conquer**
  - Efficient trivial accept and trivial reject
  - Non-trivial case: divide and test
- **Outcodes of points:**
  - Bit encoding (**outcode**, OC)
    - Each edge defines a half space
    - Set bit, if point is outside
- **Trivial cases**
  - Trivial accept:
    - $(OC(p_a) \text{ OR } OC(p_e)) = 0$
  - Trivial reject:
    - $(OC(p_a) \text{ AND } OC(p_e)) \neq 0$
  - Edges has to be clipped to all edges where bits are set:
    - $OC(p_a) \text{ XOR } OC(p_e)$



Bit order: **T**op, **B**ottom, Right, Left

**Viewport** ( $x_{\min}$ ,  $y_{\min}$ ,  $x_{\max}$ ,  $y_{\max}$ )

# Cohen-Sutherland

- **Clipping**

```
... // trivial cases
```

```
for each vertex p
```

```
  oc= OC(p)
```

```
  for each edge e
```

```
    if (oc[e]) {
```

```
      p= cut(p,e);
```

```
      oc= OC(p);
```

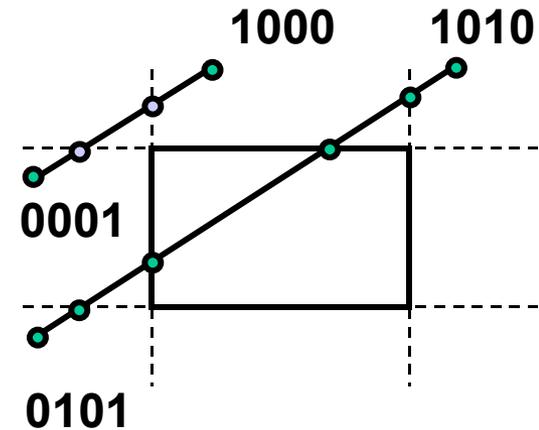
```
    }
```

```
  Reject, if point outside
```

- **Intersection calculation for  $x=x_{\min}$**

$$\frac{y - y_a}{y_e - y_a} = \frac{x - x_a}{x_e - x_a}$$

$$y = y_a + (x - x_a) \frac{y_e - y_a}{x_e - x_a}$$



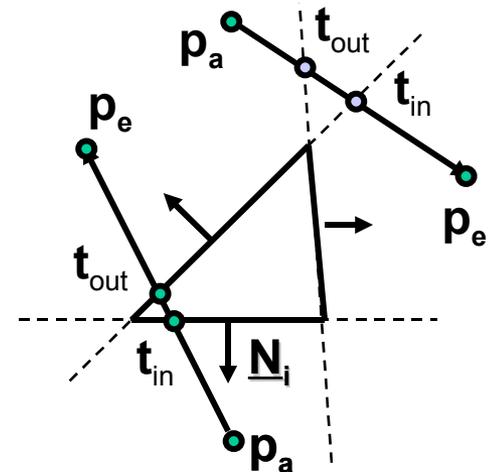
# Cyrus-Beck ('78)

- **Parametric line-clipping algorithm**

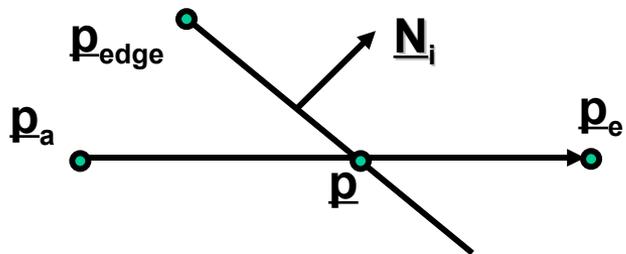
- Only convex polygons: max. 2 intersection points
- Use edge orientation

- **Idea:**

- Clipping line  $\underline{p}_a + t_i(\underline{p}_e - \underline{p}_a)$  with each edge
- Intersection points sorted by parameter  $t_i$
- Select
  - $t_{in}$ : entry point  $((\underline{p}_e - \underline{p}_a) \cdot \underline{N}_i < 0)$  with largest  $t_i$  and
  - $t_{out}$ : exit point  $((\underline{p}_e - \underline{p}_a) \cdot \underline{N}_i > 0)$  with smallest  $t_i$
- If  $t_{out} < t_{in}$ , line lies completely outside



- **Intersection calculation:**



$$\begin{aligned} (p - p_{edge}) \cdot N_i &= 0 \\ t_i (p_e - p_a) \cdot N_i + (p_a - p_{edge}) \cdot N_i &= 0 \\ t_i &= \frac{(p_{edge} - p_a) \cdot N_i}{(p_e - p_a) \cdot N_i} \end{aligned}$$

# Liang-Barsky ('84)

- **Cyrus-Beck for axis-parallel rectangles**

- Using Window-Edge-Coordinates (with respect to an edge T)

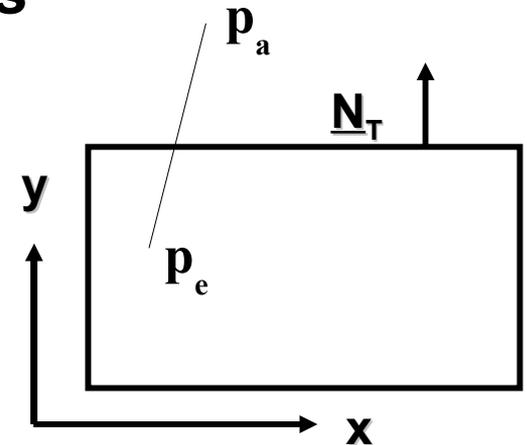
$$WEC_T(p) = (p - p_T) \cdot N_T$$

- **Example: top ( $y = y_{max}$ )**

$$N_T = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, p_a - p_T = \begin{pmatrix} x_a - x_{max} \\ y_a - y_{max} \end{pmatrix}$$

$$t_T = \frac{(p_a - p_T) \cdot N_T}{(p_a - p_e) \cdot N_T} = \frac{WEC_T(p_a)}{WEC_T(p_a) - WEC_T(p_e)} = \frac{y_a - y_{max}}{y_a - y_e}$$

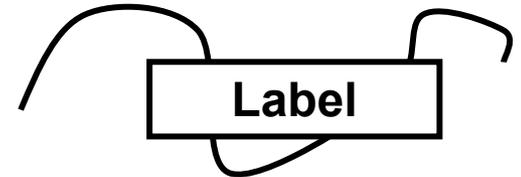
- Window-Edge-Coordinate (WEC): Decision function for an edge
  - Directed distance to edge
    - Only sign matters, similar to Cohen-Sutherland opcode
  - Sign of the dot product determines whether the point is in or out
  - Normalization unimportant



# Enhancements CB-Clipping

- **Outer clipping (exterior clipping, covering)**

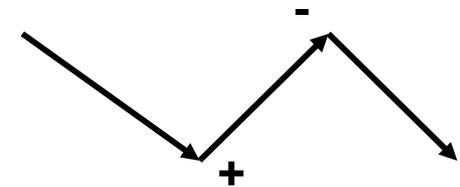
- Inversion of clipping: max. 2 segments per line
- Examples: window systems, labels, ...



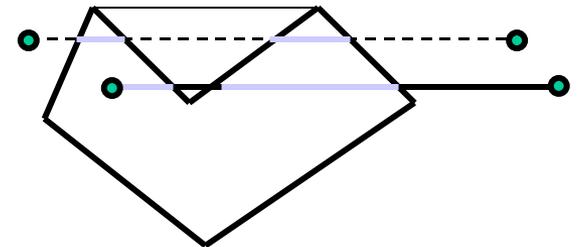
- **Concave region clipping**

- Detection of convexity
  - Cross product of adjacent (non-colinear) segments changes sign
- Procedure

- Add regions to make it convex
  - inner clipping on the whole
  - outer clipping on additions



- Convex region gap
  - combine segments
- Jordan curve theorem
  - determines if start point is in
  - sorting all intersection points
  - generate consecutive segments



# Line clipping - Summary

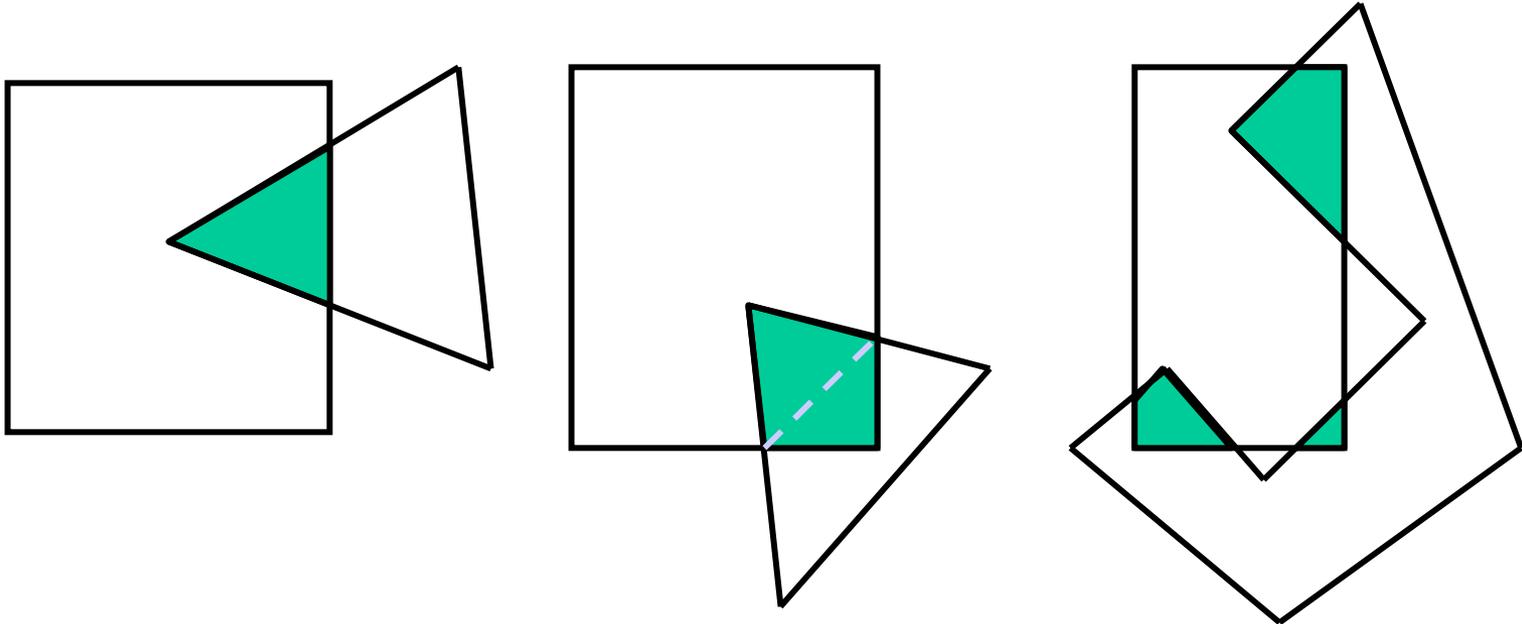
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- **Cohen-Sutherland, Cyrus-Beck, and Liang-Barsky algorithms readily extend to 3D**
- **Cohen-Sutherland algorithm**
  - + Efficient when a majority of lines can trivially be accepted or rejected
    - Very large clip rectangles: almost all lines inside
    - Very small clip rectangles: almost all lines outside
  - Repeated clipping for remaining lines
  - Testing for 2D/3D point coordinates
- **Cyrus-Beck (Liang-Barsky) algorithms**
  - + Efficient when many lines must be clipped
  - + Testing for 1D parameter values
  - Testing intersections always for all clipping edges (in the Liang-Barsky trivial rejection testing possible)

# Polygon Clipping

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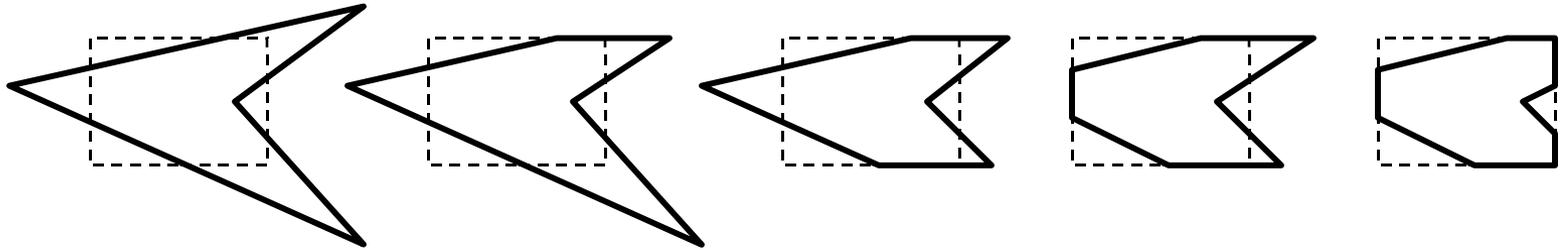
- **Extending line clipping**
  - Polygons have to remain closed
    - Filling, hatching, shading, ...



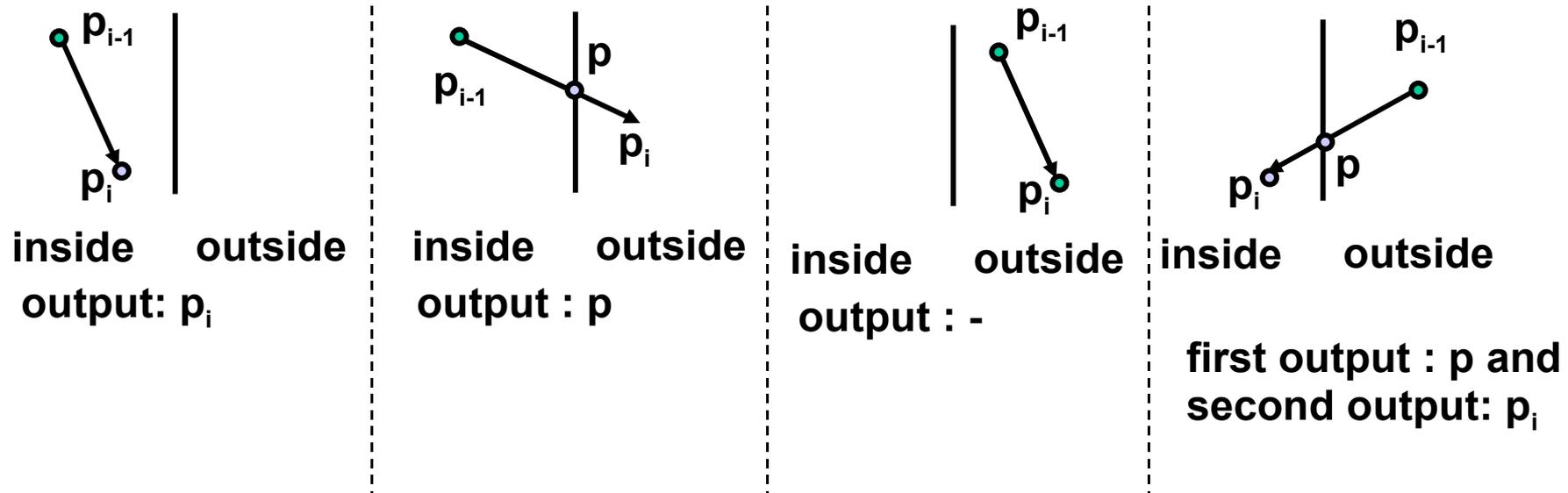
# Sutherland-Hodgeman ('74)

- **Idea:**

- Iterative clipping against each clipping line



- Local operations on  $p_{i-1}$  and  $p_i$

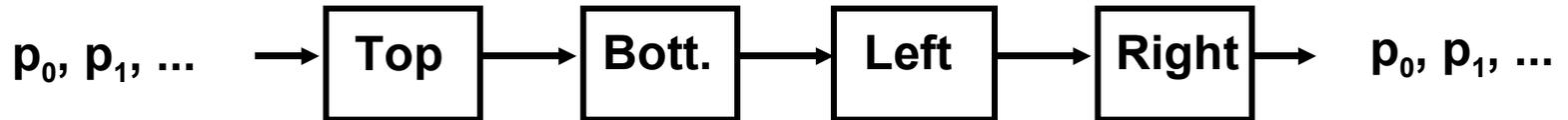


# Enhancements

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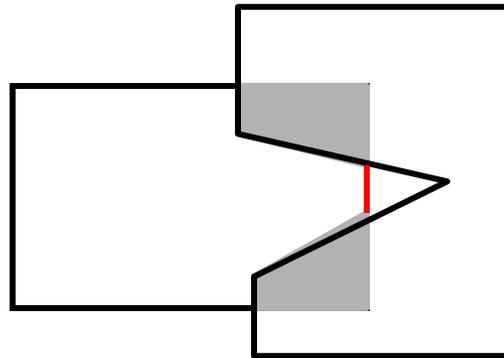
- **Recursive polygon clipping**

- Pipelined Sutherland-Hodgeman



- **Problems**

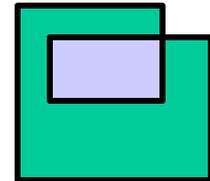
- Degenerated polygons/edges
  - Elimination by post-processing, if necessary



# Other clipping algorithms

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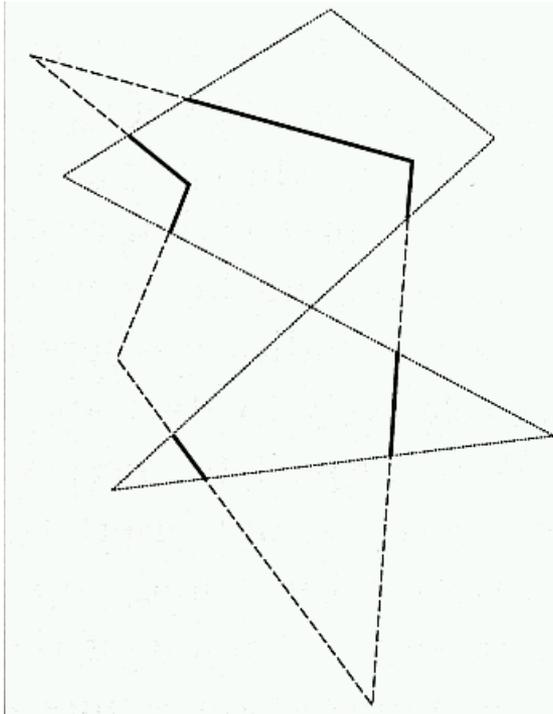
- **Weiler & Atherton ('77)**
  - Arbitrary concave polygons with holes against each other
- **Vatti ('92)**
  - Also with self-overlap
- **Greiner & Hormann (TOG '98)**
  - Simpler and faster as Vatti
  - Also supports boolean operations
  - Idea:
    - Odd winding number rule
      - Intersection with the polygon leads to a winding number  $\pm 1$
    - Walk along both polygons
    - Alternate winding number
    - Mark point of entry and point of exit
    - Combine results



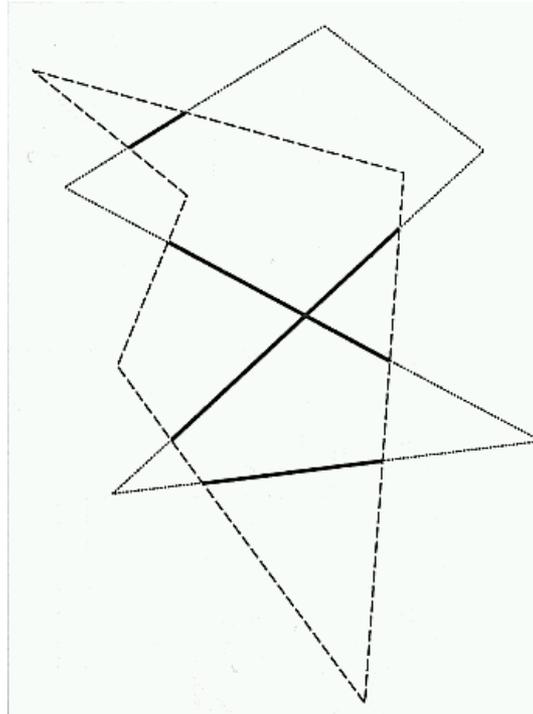
Non-zero WN: In  
Odd WN: Out

# Greiner & Hormann

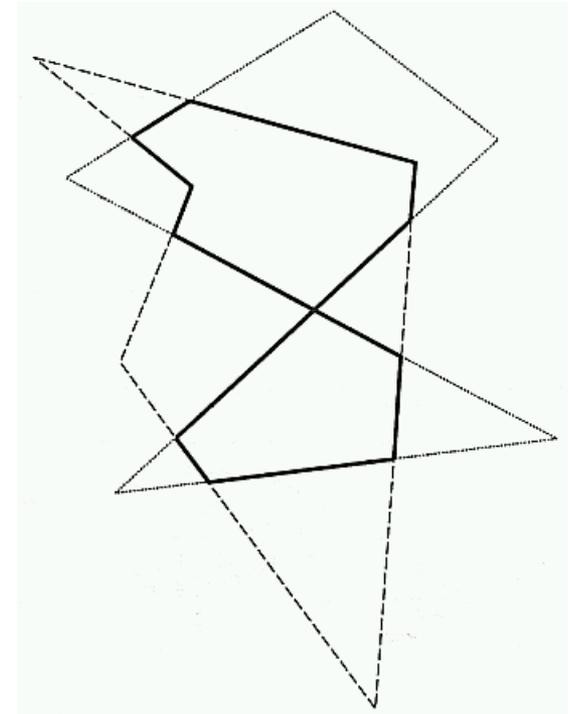
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A in B



B in A



$(A \text{ in } B) \cup (B \text{ in } A)$

# 3D clipping against view volume

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- **Requirements**

- Avoid unnecessary rasterization
- Avoid overflow on transformation at fixed point !

- **Clipping against viewing frustum**

- Enhanced Cohen-Sutherland with 6-bit outcode
- After perspective division
  - $-1 < y < 1$
  - $-1 < x < 1$
  - $-1 < z < 0$
- Clip against side planes of the viewing frustum
- Works analogous with Liang-Barsky or Sutherland-Hodgeman

# 3D clipping against view volume

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- **Clipping in homogeneous coordinates**

- Avoid division by  $w$
- Inside test with a linear distance function (WEC)
  - Left:  $X/W > -1$        $\rightarrow W+X = WEC_L(\underline{p}) > 0$
  - Top:  $Y/W < 1$        $\rightarrow W - Y = WEC_T(\underline{p}) > 0$
  - Back:  $Z/W > -1$        $\rightarrow W+Z = WEC_B(\underline{p}) > 0$
  - ...
- Intersection point calculation
  - Test:  $WEC_L(\underline{p}_a) > 0$  and  $WEC_L(\underline{p}_e) < 0$
  - Calculation:

$$WEC(\underline{p}_a + t(\underline{p}_e - \underline{p}_a)) = 0$$

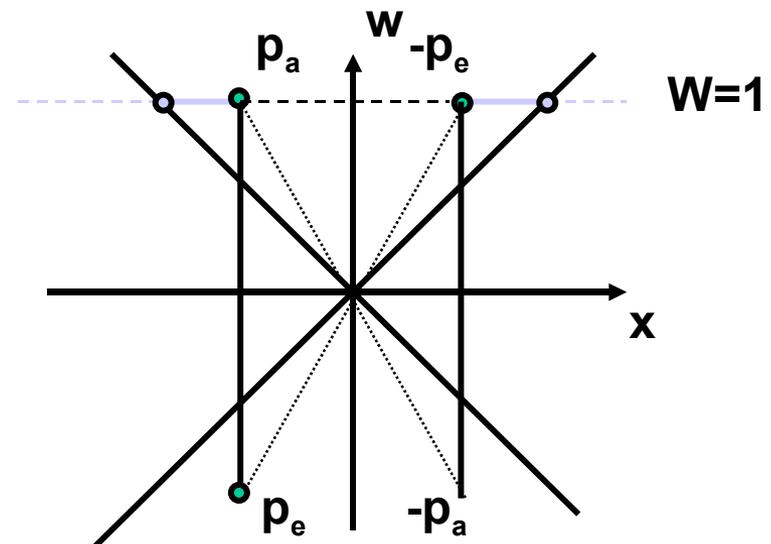
$$W_a + t(W_e - W_a) + X_a + t(X_e - X_a) = 0$$

$$t = \frac{W_a + X_a}{(W_a + X_a) - (W_e + X_e)} = \frac{WEC_L(\underline{p}_a)}{WEC_L(\underline{p}_a) - WEC_L(\underline{p}_e)}$$

# Problems with Homog. Coord.

- **Negative w**

- Points with  $w < 0$  or lines with  $w_a < 0$  and  $w_e < 0$ 
  - Negate and continue
- Lines with  $w_a \cdot w_e < 0$  (NURBS)
  - Line moves through infinity
    - External line
  - Clipping two times
    - Original Line
    - Negated line
  - Generates up to two segments



# Practical implementations

- **Combining clipping and scissoring**

- Clipping is expensive and should be avoided
  - Intersection calculation
  - Variable number of new points
- Enlargement of clipping region
  - Larger than viewport, but
  - Still avoiding overflow due to fixed-point representation
- Result
  - Less clipping
  - Applications should avoid drawing objects which are lying outside of the viewing frustum
  - Objects which are lying partially outside will be clipped implicitly during rasterization.

