

Lecture 23:

Curvature-Based Morphology II: Affine Morphological Scale-Space

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Motivation

Motivation

- ◆ In Lecture 22, we have considered the mean curvature motion

$$\partial_t u = |\nabla u| \operatorname{curv}(u).$$

- ◆ The corresponding curve evolution could be written as

$$\partial_t \mathbf{c}(p, t) = \partial_{\nu\nu} \mathbf{c}(p, t)$$

where ν is the Euclidean invariant arc-length.

- ◆ Is it possible to find related evolutions that are not only invariant under Euclidean transformations (rotations, translations), but also under affine ones ?

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Affine Morphological Scale-Space

Affine Transformations:

- ◆ given by

$$\mathbf{x} \mapsto A\mathbf{x} + \mathbf{b}$$

where $\mathbf{b} \in \mathbb{R}^2$ is a translation vector and $A \in \mathbb{R}^{2 \times 2}$ is invertible.

- ◆ arise as shape distortions of planar objects when being observed from a large distance under different angles

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Affine Invariant Intrinsic Diffusion

(Sapiro/Tannenbaum 1993)

- ◆ Idea: replace Euclidean arc-length v in intrinsic heat flow

$$\partial_t \mathbf{c}(p, t) = \partial_{vv} \mathbf{c}(p, t)$$

by an "*affine invariant arc-length*" (Blaschke 1923)

$$s(p, t) := \int_0^p \left(\det(\mathbf{c}_\rho(\rho, t), \mathbf{c}_{\rho\rho}(\rho, t)) \right)^{\frac{1}{3}} d\rho.$$

- ◆ By virtue of

$$\partial_{ss} \mathbf{c}(p, t) = (\kappa(p, t))^{\frac{1}{3}} \mathbf{n}(p, t)$$

one gets the *affine invariant heat flow (affine shortening flow)*

$$\partial_t \mathbf{c}(p, t) = (\kappa(p, t))^{\frac{1}{3}} \mathbf{n}(p, t).$$

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Affine Morphological Scale-Space (3)

Corresponding Affine Invariant Image Evolution

(Alvarez/Guichard/Lions/Morel 1993)

- ◆ follows the PDE

$$\partial_t u = |\nabla u| (\text{curv}(u))^{\frac{1}{3}}$$

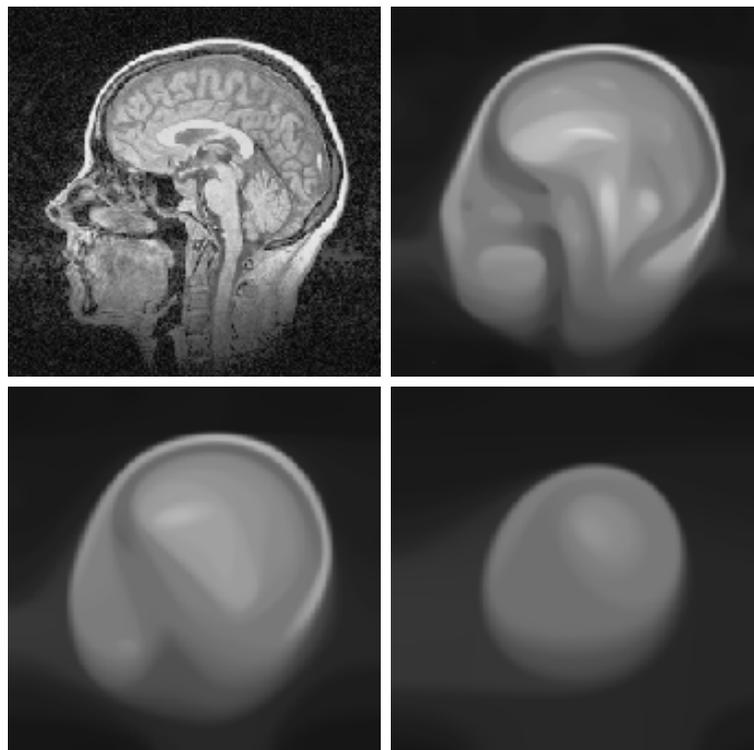
- ◆ can be rewritten as

$$\begin{aligned} \partial_t u &= (u_y^2 u_{xx} - 2u_x u_y u_{xy} + u_x^2 u_{yy})^{\frac{1}{3}} \\ &= |\nabla u|^{\frac{2}{3}} u_{\xi\xi}^{\frac{1}{3}} \end{aligned}$$

- ◆ This evolution is called *affine morphological scale-space (AMSS)*.
- ◆ Alvarez et al. showed in an axiomatic way that it is the unique affine invariant scale-space.
- ◆ Since it has more invariances than other scale-spaces, they named it *fundamental equation in image processing*.

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Affine Morphological Scale-Space (4)



Affine morphological scale-space. (a) **Top left:** Original image, $\Omega = (0, 236)^2$. (b) **Top right:** $t = 20$. (c) **Bottom left:** $t = 50$. (d) **Bottom right:** $t = 140$.

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Theoretical Results

basically same as for MCM, with the following exceptions:

- ◆ Closed curves shrink to *elliptical points*.
- ◆ Ellipses maintain their eccentricity during shrinkage.
- ◆ time for shrinking a circle of radius σ (or ellipse of area $\pi\sigma^2$) to a point:

$$T = \frac{3}{4}\sigma^{\frac{4}{3}}$$

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Numerical Scheme

- ◆ Typically one uses the equation

$$u_t = (u_y^2 u_{xx} - 2u_x u_y u_{xy} + u_x^2 u_{yy})^{\frac{1}{3}}$$

replaces u_t by forward differences, and the spatial derivatives by central differences.

- ◆ no stability theory available for this explicit scheme; can violate extremum principle
- ◆ typical step size for experimental stability ($h_1 = h_2 = 1$):

$$\tau \leq 0.1.$$

- ◆ However, a good approximation of affine invariance may require much smaller time steps, for instance

$$\tau \leq 0.01.$$

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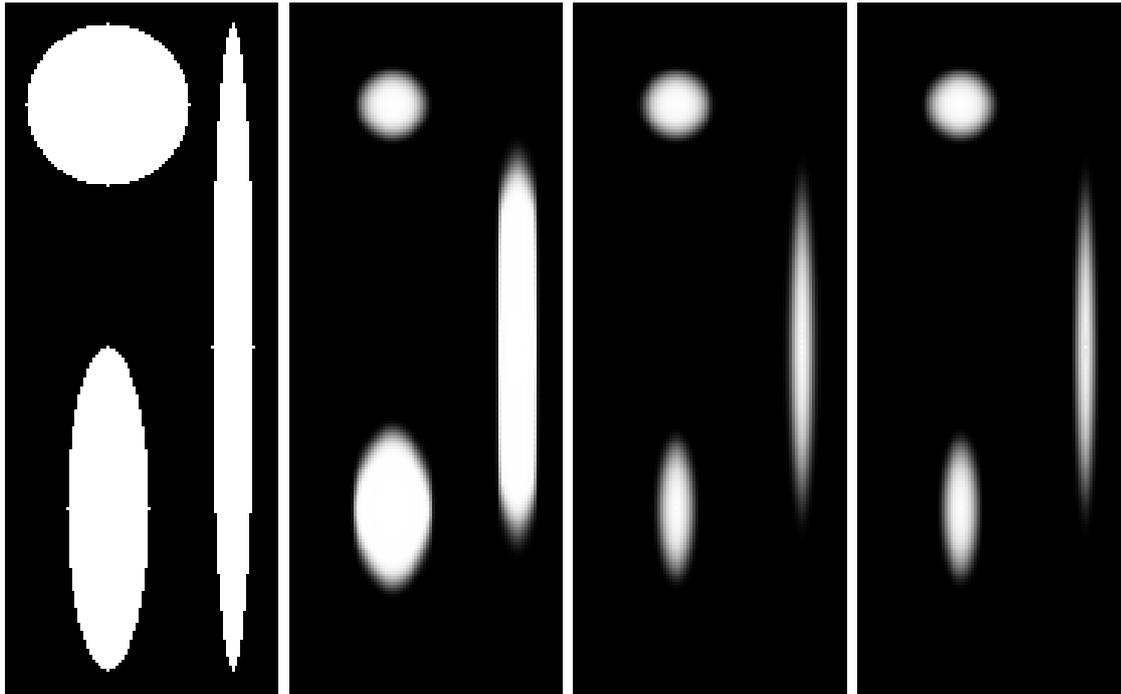
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Test of affine invariance of an explicit scheme for AMSS. (a) **Left:** Original image with four ellipses of equal area, $\Omega = (0, 94) \times (0, 240)$. Under AMSS, these ellipses should keep their eccentricity. (b) **Middle left:** Result with 500 iterations of time step size $\tau = 0.1$. (c) **Middle right:** 5000 iterations with $\tau = 0.01$. (d) **Right:** 50000 iterations with $\tau = 0.001$.

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Extensions

Extensions

Three-Dimensional AMSS

(Caselles/Sbert 1996)

- ◆ is given by the equation

$$\partial_t u = |\nabla u| \operatorname{sgn}(\kappa_1) (\kappa_1 \kappa_2)^{1/4}$$

(κ_1, κ_2 : principal curvatures of isosurface)

- ◆ In contrast to 2-D, topological changes may occur (remnescent of diffusion filters when going from 1-D to 2-D)

AMSS for Movies

(Guichard 1998)

- ◆ There exists also a unique morphological, affine, and Galilean invariant scale-space for movies.
- ◆ can also be justified in an axiomatic way

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Application: Corner Detection

(Alvarez/Morales 1997)

Problems

- ◆ Corner detection is sensitive to noise.
- ◆ Embedding into Gaussian scale-space increases robustness, but dislocates corners.
- ◆ Corners cannot always be traced back in scale (Sporring et al. 2000).

Goal

- ◆ embedding of corner detection into a better suited scale-space with a well-founded downfocusing strategy

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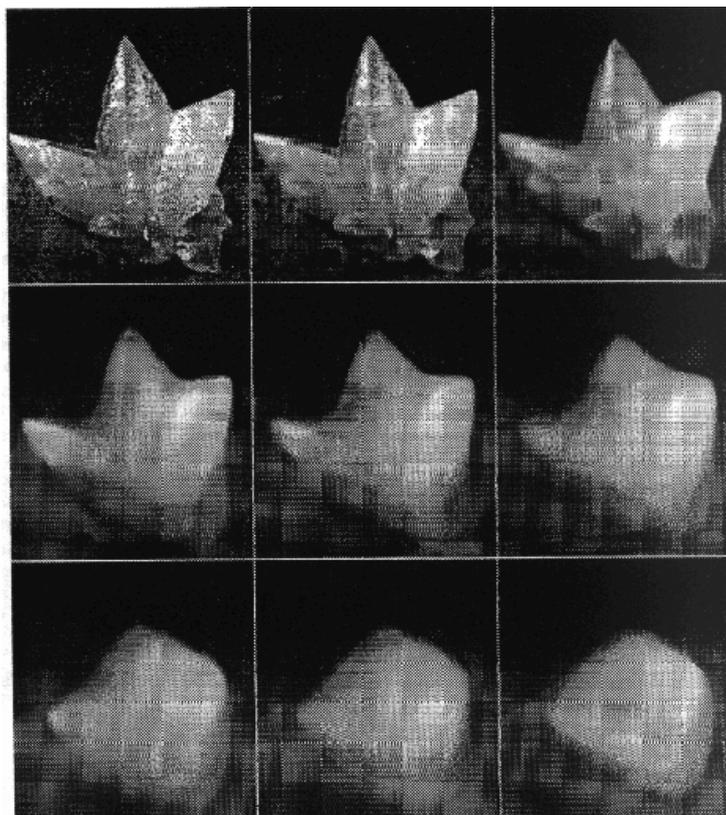
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Evolution of a crystal under AMSS. **Authors:** L. Alvarez and F. Morales (1997).

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Application: Corner Detection (3)

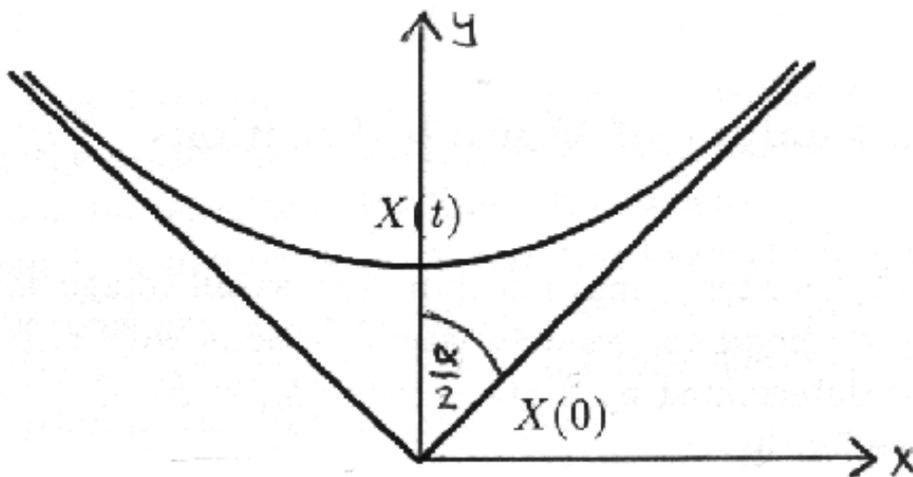
Method

- ◆ create a stack of images in AMSS
- ◆ identify corners as curvature extrema of isophotes
- ◆ start with significant corners at a coarse scale
- ◆ analytical (!) results from the theory of AMSS (p. 15):
 - corners move along a line
 - speed is a simple function of corner angleallow to extrapolate corner location and angle to scale $t = 0$

Why AMSS ?

- ◆ curvature-based morphological scale-spaces cannot create new corners: number of curvature extrema is nonincreasing
- ◆ affine invariance guarantees that: all corners evolve in the same manner (but with different speed), because different angles can be transformed into each other by affine transformations

Application: Corner Detection (4)



Under AMSS, a corner becomes a hyperbola. **Authors:** L. Alvarez and F. Morales (1997).

Application: Corner Detection (5)

Corner evolution under AMSS

- ◆ Evolution of the previous corner with angle α under the (temporally rescaled) AMSS

$$u_t = t^{1/3} (u_y^2 u_{xx} - 2u_x u_y u_{xy} + u_x^2 u_{yy})^{1/3}$$

is analytically given by the hyperbola

$$y = \lambda \sqrt{t^2 + \lambda^2 x^2}$$

with $\lambda := 1/\sqrt{\tan \frac{\alpha}{2}}$.

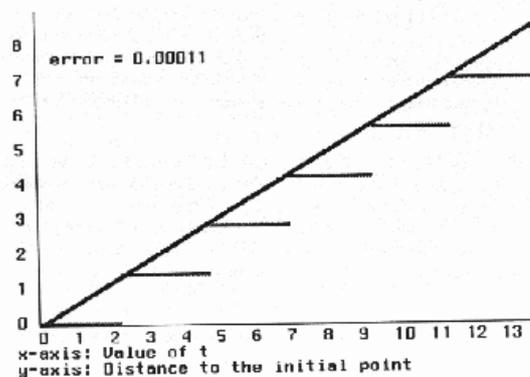
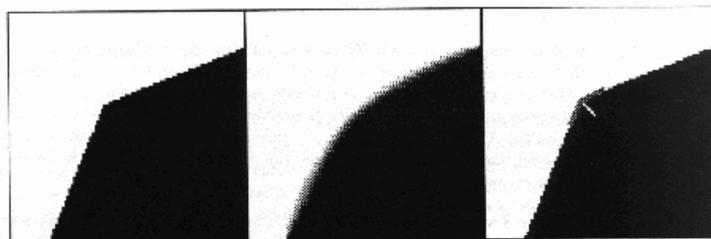
- ◆ Corners at $x = 0$ move linearly in time

$$y = \lambda t$$

where the speed $\lambda = 1/\sqrt{\tan \frac{\alpha}{2}}$ depends on the corner angle α .

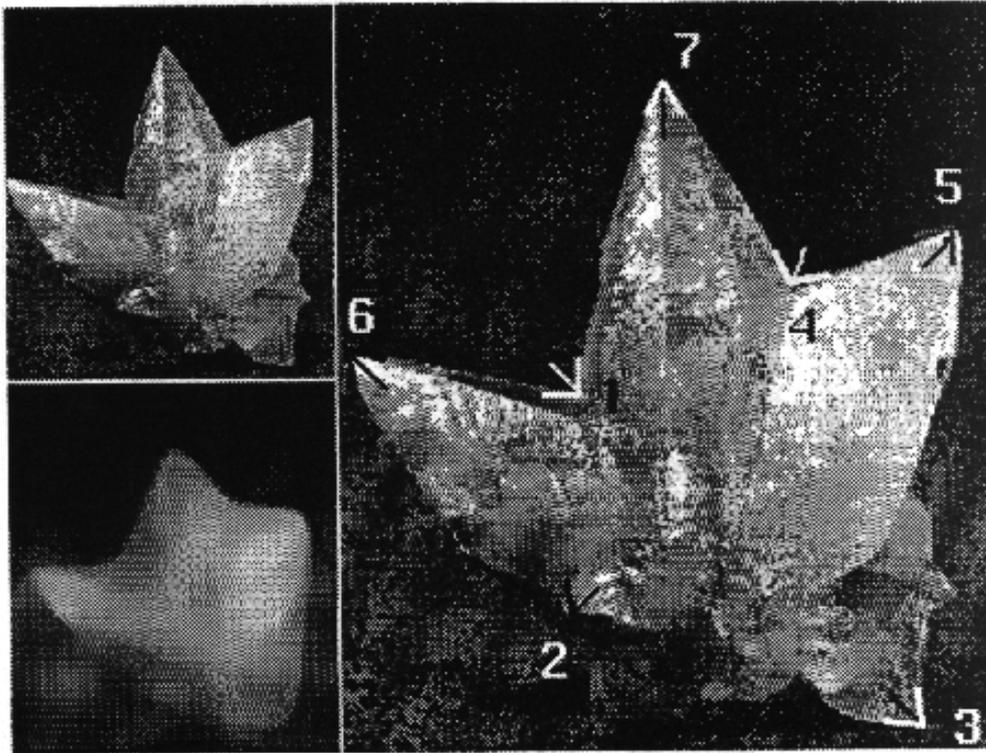
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Application: Corner Detection (6)



- (a) **Top:** From left to right: original corner, smoothed by AMSS, and extrapolated to scale $t = 0$. (b) **Bottom:** Under AMSS, the corner displacement is a linear function in time. This allows extrapolation to the initial location at $t = 0$. **Authors:** L. Alvarez and F. Morales (1997).

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(a) **Left:** Crystal image and AMSS-smoothed version. (b) **Right:** The seven most significant corners after linear extrapolation. **Authors:** L. Alvarez and F. Morales (1997).

Summary

Summary

- ◆ Affine morphological scale-space (AMSS) is the affine invariant analogue to mean curvature motion (MCM).
- ◆ Level lines follow an intrinsic heat equation where the Euclidean arc length is replaced by an affine invariant one.
- ◆ The corresponding image evolution can be derived in an axiomatic way.
- ◆ similar theoretical properties as MCM
- ◆ numerically difficult, if good approximations to affine invariance are required
- ◆ AMSS for corner detection:
 - identifies corners at coarse scale (as curvature maxima)
 - analytical formula for stable extrapolation to $t = 0$
 - AMSS guarantees that all corners evolve in the same way

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Assignment C6 (1)

Assignment C6 – Classroom Work

Problem 1 (Continuous-Scale Morphology Morphology)

In Lecture 20, we have seen that dilation with disc-shaped structuring elements of radius t can be understood as curve evolution

$$\partial_t c = \mathbf{n}$$

or as image evolution

$$\partial_t u = \nabla u .$$

Determine the evolution equations for dilation with a family of structuring elements whose shape is given as an ellipse.

For simplicity, you can first start with an ellipse aligned to the coordinate system and the half-axes a and b . More general ellipses can be obtained by rotation.

Is there a more elegant and general way to express the ellipses and the evolution?

Assignment C6 (2)



Problem 2 (Numerical Schemes for Continuous-Scale Morphology)

We deal with the scheme of Osher and Sethian for continuous-scale morphology. Consider the 1-D case with $h = 1.0$, $\tau = 0.5$ and the following initial data:

$$f_i = \begin{cases} 1 & : i \leq 0, \\ 0 & : \text{else.} \end{cases}$$

Consider also a set-based scheme for dilation/erosion. Compare and discuss the results of the following procedures.

- (a) With the set-based scheme. Perform exactly one dilation step.
- (b) With the set-based scheme. Perform (i) at first one dilation step followed by (ii) one erosion step.
- (c) With the Osher-Sethian scheme. Perform two dilation steps.
- (d) With the Osher-Sethian scheme. Perform (i) at first one dilation step followed by (ii) one erosion step.

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