

Lecture 7:

Nonlinear Anisotropic Diffusion I: Modelling

Contents

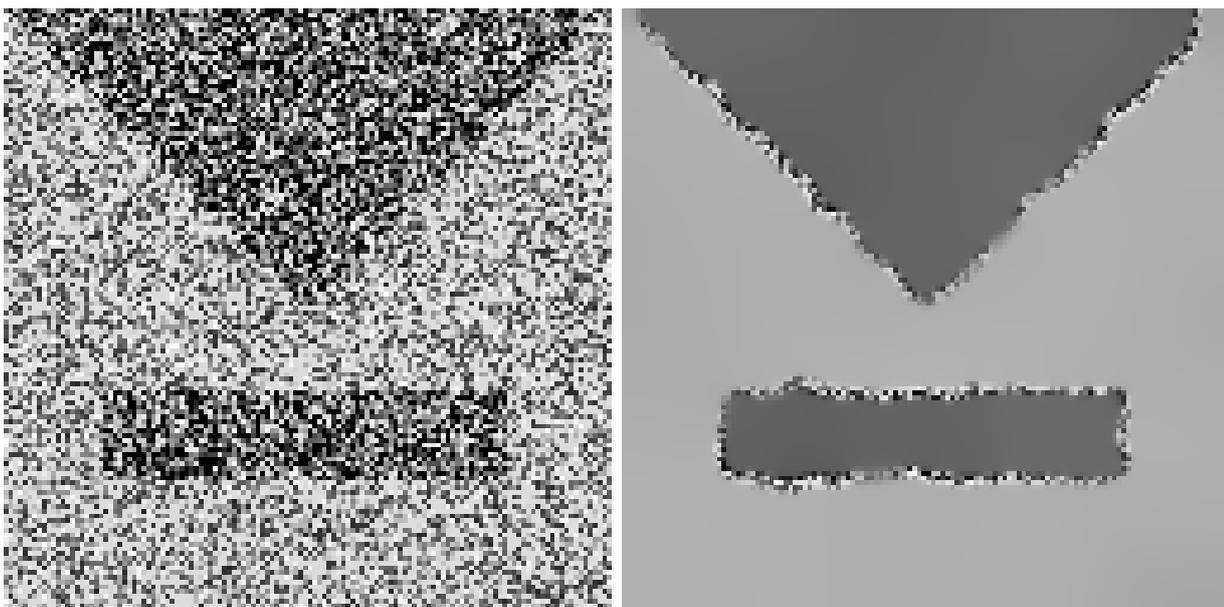
1. Why Anisotropic?
2. Edge-Enhancing Anisotropic Diffusion
3. Analysing Local Structure
4. Coherence-Enhancing Anisotropic Diffusion

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Why Anisotropic? (1)

Why Anisotropic?



(a) **Left:** Test image, $\Omega = (0, 128)^2$. (b) **Right:** Isotropic nonlinear diffusion is not optimal when noise at edges is to be removed ($\lambda = 3.5$, $\sigma = 3$, $t = 80$).

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Why Anisotropic? (2)



Fingerprint processing. (a) **Left:** Original fingerprint, $\Omega = (0, 256)^2$. (b) **Right:** Isotropic nonlinear diffusion cannot close interrupted lines ($\sigma = 1, \lambda = 4, t = 20$).

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Why Anisotropic? (3)

Isotropic nonlinear diffusion filters

- ◆ can have difficulties with noisy edges
- ◆ cannot enhance coherent flow-like structures

Improved filters must take into account the *direction* of the local structure.

→ requires a diffusion tensor instead of scalar-valued diffusivity

→ local structure specifies its eigenvectors and eigenvalues

- Two examples:**
1. Noise elimination with edge enhancement
 2. Enhancement of coherent structures

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Edge-Enhancing Anisotropic Diffusion (EED)

Goals:

- ◆ smooth preferently within regions
- ◆ inhibit diffusion perpendicular to edges

Choice of the Diffusion Tensor

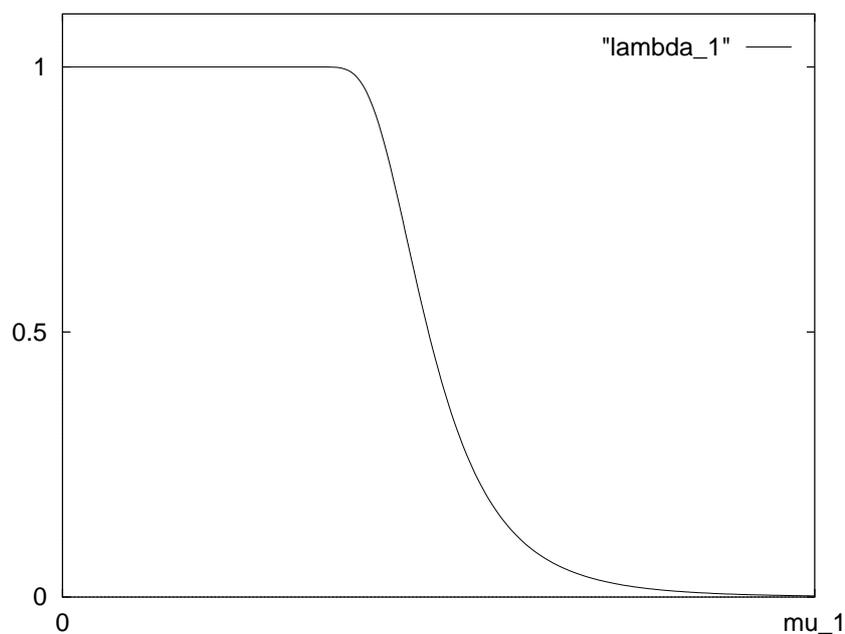
Eigenvectors: $v_1 \parallel \nabla u_\sigma$, $v_2 \perp \nabla u_\sigma$ (normalised)

Eigenvalues: diffusion along edge: $\lambda_2 := 1$
 diffusion across edge: $\lambda_1 := g(|\nabla u_\sigma|^2)$
 with a diffusivity g as before.

The eigenvectors v_1 , v_2 and their eigenvalues λ_1 , λ_2 determine the diffusion tensor:

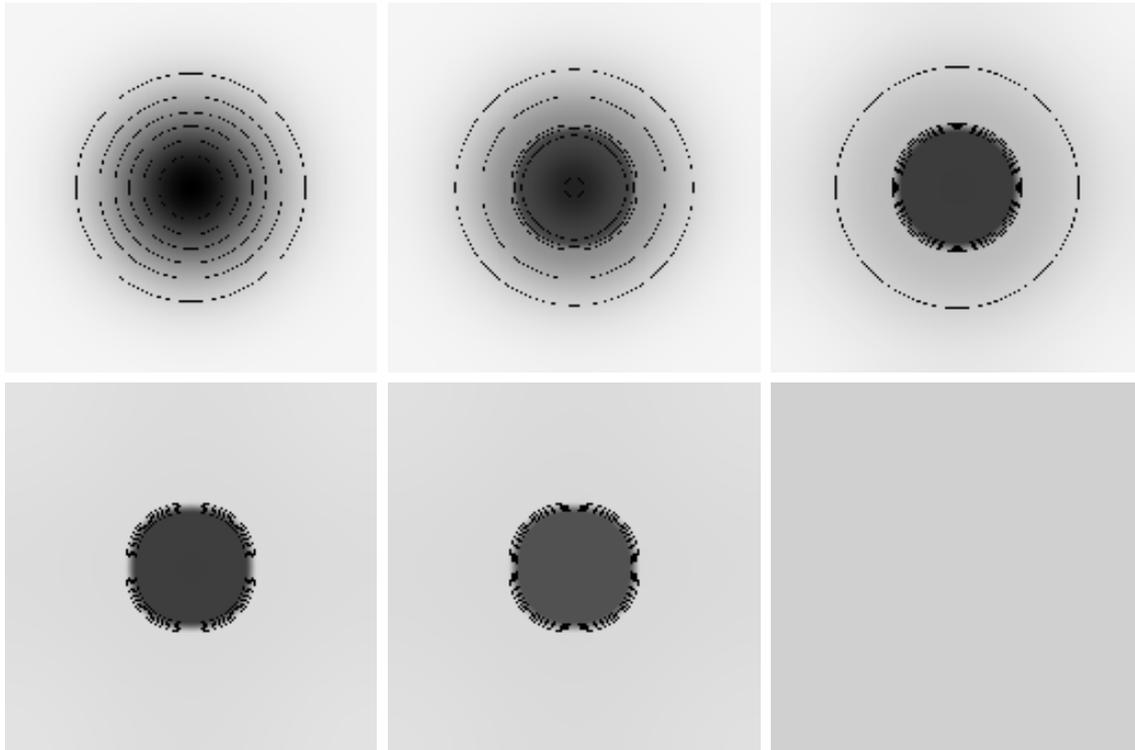
$$D(\nabla u_\sigma) := (v_1 | v_2) \operatorname{diag}(\lambda_1, \lambda_2) \begin{pmatrix} v_1^\top \\ v_2^\top \end{pmatrix}$$

Edge-Enhancing Anisotropic Diffusion (2)



For edge-enhancing diffusion, the eigenvalue λ_1 determines diffusion across the edge. It is a smooth, decreasing function of the image contrast $|\nabla u_\sigma|^2$.

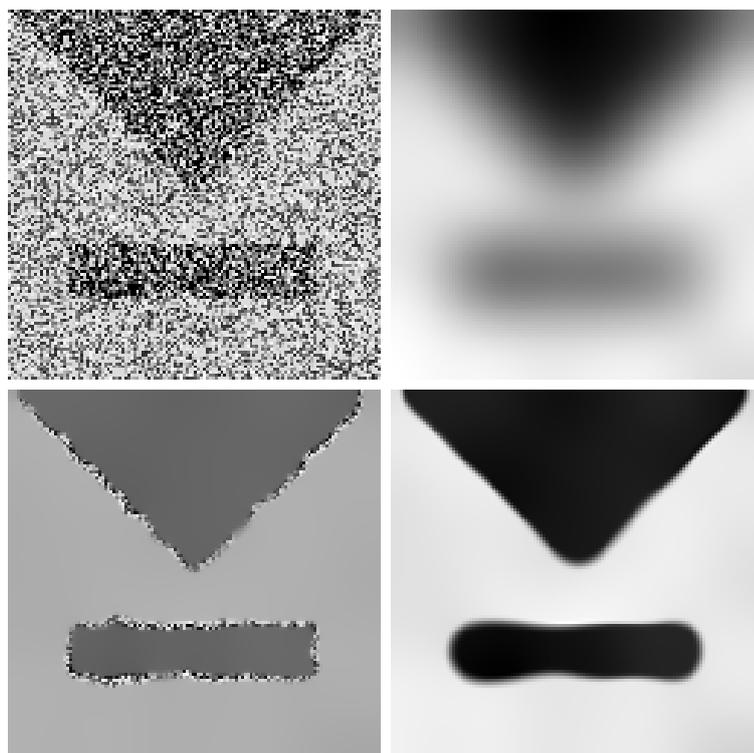
Edge-Enhancing Anisotropic Diffusion (3)



Edge-enhancing anisotropic diffusion filtering of a Gaussian-type function, $\Omega = (0, 256)^2$, $\lambda = 3.6$, $\sigma = 2$. **From top left to bottom right:** $t = 0, 125, 625, 3125, 15625, 78125$.

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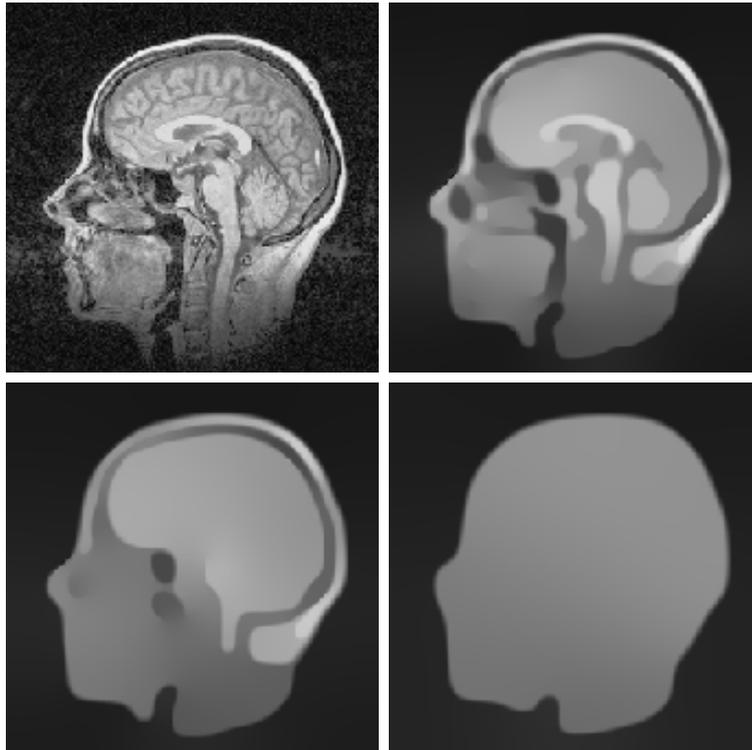
Edge-Enhancing Anisotropic Diffusion (4)



Restoration properties of diffusion filters. (a) **Top left:** Test image, $\Omega = (0, 128)^2$. (b) **Top right:** Linear diffusion, $t = 80$. (c) **Bottom left:** Nonlinear isotropic diffusion, $\lambda = 3.5$, $\sigma = 3$, $t = 80$. (d) **Bottom right:** Nonlinear anisotropic diffusion, $\lambda = 3.5$, $\sigma = 3$, $t = 80$.

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Edge-Enhancing Anisotropic Diffusion (5)

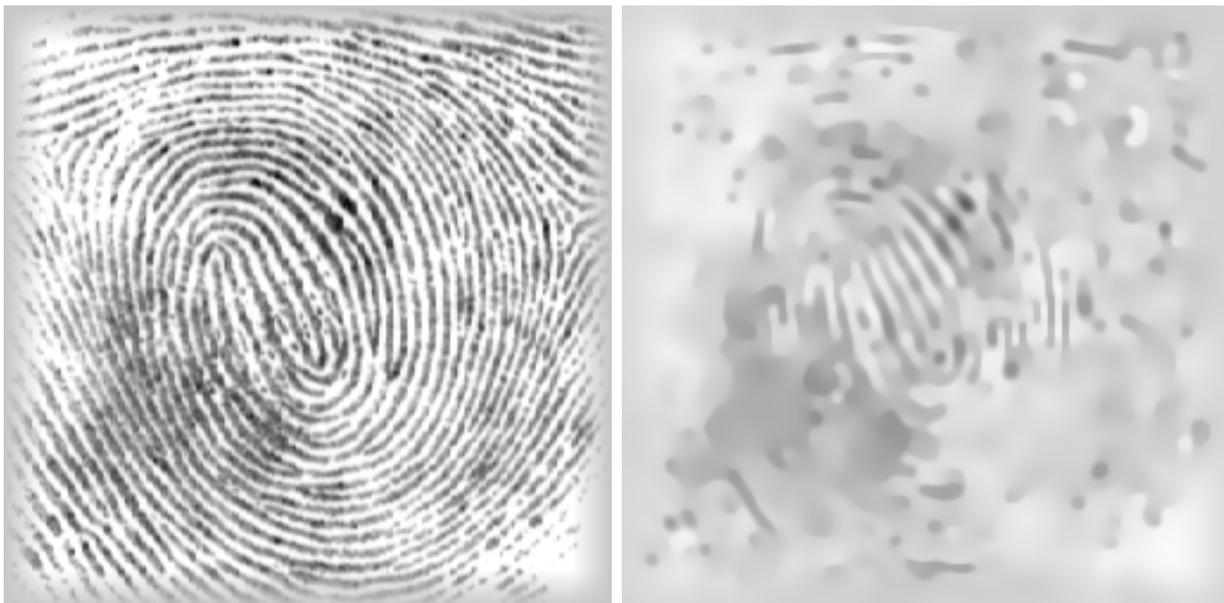


Scale-space behaviour of nonlinear anisotropic diffusion filtering ($\lambda = 3$, $\sigma = 1$). (a) **Top left:** Original image, $\Omega = (0, 236)^2$. (b) **Top right:** $t = 250$. (c) **Bottom left:** $t = 875$. (d) **Bottom right:** $t = 3000$.

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Edge-Enhancing Anisotropic Diffusion (6)

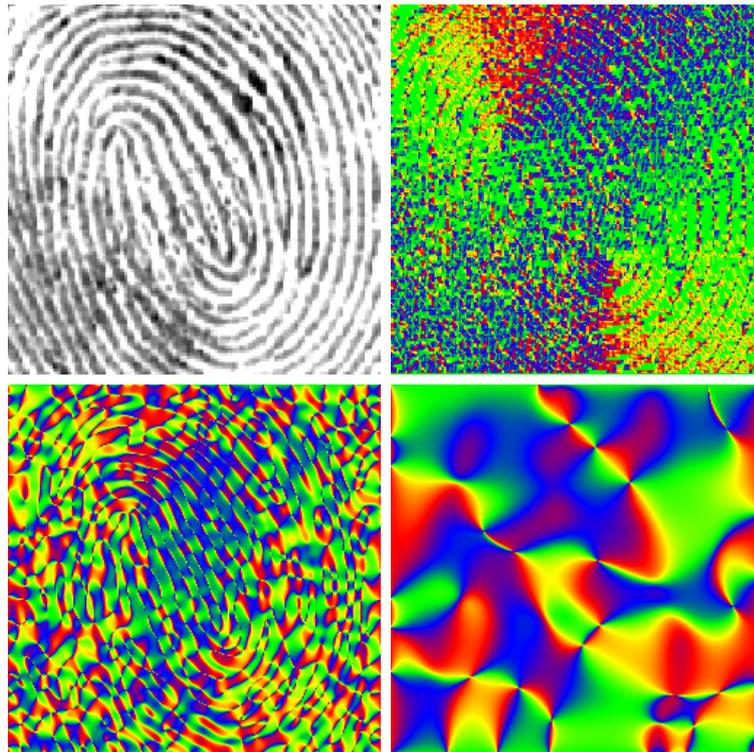
Limitations



EED is not good for closing interrupted lines in flow-like structures. (a) **Left:** Original fingerprint, $\Omega = (0, 256)^2$. (b) **Right:** Edge-enhancing anisotropic diffusion, $\sigma = 1$, $\lambda = 4$, $t = 20$.

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Edge-Enhancing Anisotropic Diffusion (7)



Analysis of the regularised gradient direction. (a) **Top left:** Original image, $\Omega = (0, 256)^2$. (b) **Top right:** Gradient direction, colour coded. (c) **Bottom left:** Gradient direction after Gaussian convolution with $\sigma = 4$. (d) **Bottom right:** $\sigma = 16$.

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Edge-Enhancing Anisotropic Diffusion (8)

EED is not good for closing interrupted lines in flow-like structures. It seems that the diffusion goes in inappropriate directions.

Reason

- ◆ large convolution kernels cancel adjacent gradients with the same direction but opposite orientation
- ◆ resulting smoothed flow field is of no use

⇒ need more sophisticated structure descriptor:
structure tensor

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Analysing Local Structure

Smoothed image gradient $\nabla u_\sigma := \nabla K_\sigma * u$ is not optimal:

- ◆ small σ : sensitive to noise
- ◆ large σ : cancellation of adjacent gradients having the same direction, but opposite orientation.

Remedy: (Förstner/Gülch 1987)

- ◆ Consider the matrix $\nabla u_\sigma \nabla u_\sigma^\top$ instead of ∇u_σ .
This solves the cancellation problem since $\nabla u_\sigma \nabla u_\sigma^\top = (-\nabla u_\sigma)(-\nabla u_\sigma^\top)$.
- ◆ Average the direction on some integration scale ρ :

$$J_\rho(\nabla u_\sigma) := K_\rho * (\nabla u_\sigma \nabla u_\sigma^\top)$$

This matrix is called *structure tensor*.

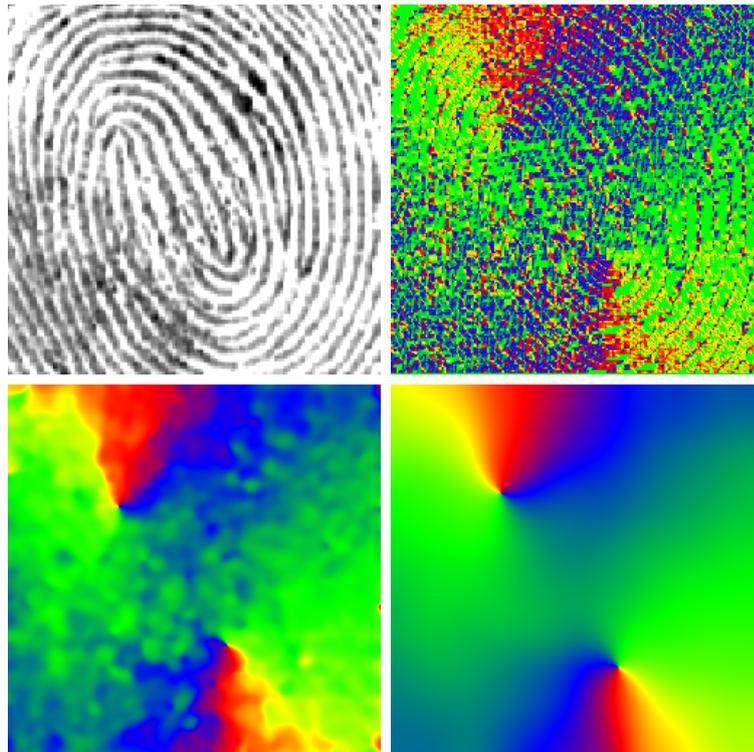
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Properties of the Structure Tensor

- ◆ J_ρ is symmetric and positive semidefinite.
- ◆ eigenvectors v_1, v_2 : preferred local structure directions
eigenvalues μ_1, μ_2 : local contrast along these directions (w.l.o.g.: $\mu_1 \geq \mu_2$)
- ◆ eigenvalues useful for analysing structures:

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|-------------------------|--------------------------|
| flat areas: | $\mu_1 = \mu_2 = 0$ |
| straight edges: | $\mu_1 \gg \mu_2 = 0$ |
| corners: | $\mu_1 \geq \mu_2 \gg 0$ |
| coherence (anisotropy): | $(\mu_1 - \mu_2)^2$ |
- ◆ two smoothing scales:
 - *noise scale* σ :
 - removes noise and small-scale details
 - should be chosen very small in order to avoid cancellation effects
 - *integration scale* ρ :
 - averages directional information
 - usually much larger than σ

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Directional analysis using the structure tensor. (a) **Top left:** Original image, $\Omega = (0, 256)^2$. (b) **Top right:** Direction of the eigenvector with the smaller eigenvalue. Integration scale: $\rho = 0$. (c) **Bottom left:** $\rho = 4$. (d) **Bottom right:** $\rho = 16$.

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Coherence-Enhancing Anisotropic Diffusion (CED)

Goals:

- ◆ smooth mainly along coherent structures (i.e. along v_2)
- ◆ increase smoothing with coherence $(\mu_1 - \mu_2)^2$

Choice of the Diffusion Tensor $D(J_\rho)$

Eigenvectors: same eigenvectors as $J_\rho(\nabla u_\sigma)$: v_1, v_2

Eigenvalues: across coherent structures:
 $\lambda_1 := \alpha$ (small $\alpha > 0$)

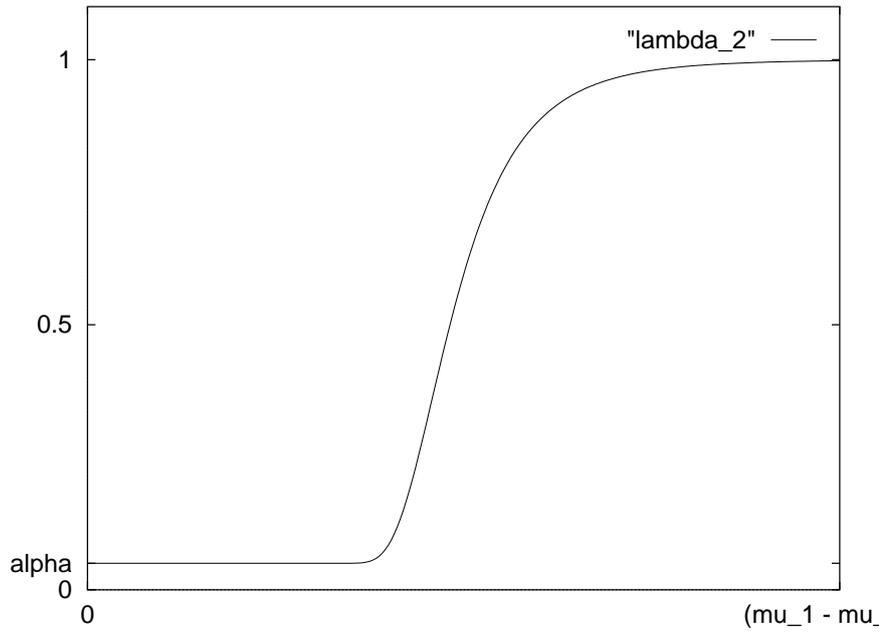
along coherent structures:

$$\lambda_2 := \begin{cases} \alpha & \text{if } \mu_1 = \mu_2, \\ \alpha + (1 - \alpha) \exp\left(\frac{-C}{(\mu_1 - \mu_2)^2}\right) & \text{else.} \end{cases}$$

The parameter $\alpha > 0$ ensures some small amount of isotropic diffusion that is required for proving well-posedness. The exp function is chosen for smoothness reasons.

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Coherence-Enhancing Anisotropic Diffusion (2)



For coherence-enhancing diffusion, the eigenvalue λ_2 determines diffusion along the coherence direction v_2 . It is a smooth, increasing function of the coherence measure $(\mu_1 - \mu_2)^2$.

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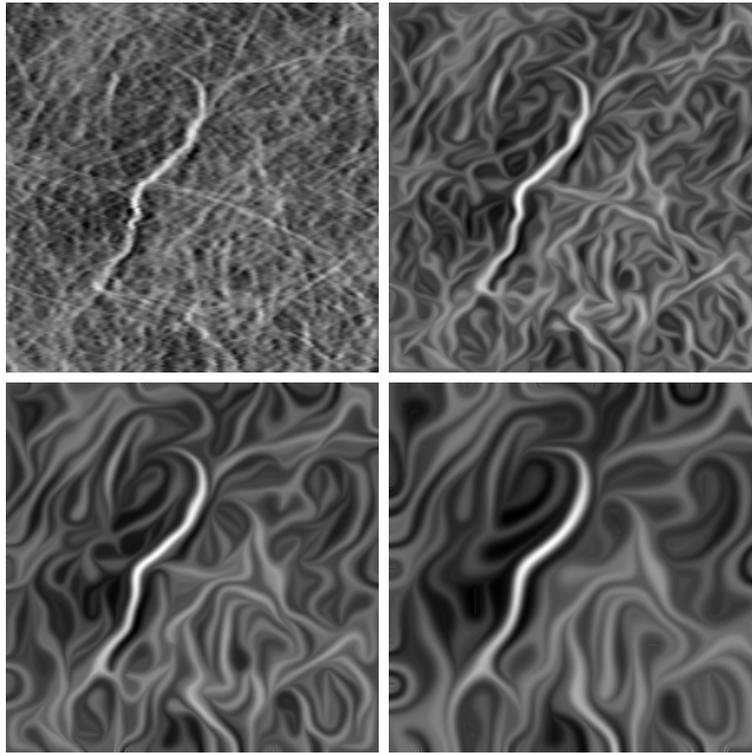
Coherence-Enhancing Anisotropic Diffusion (3)



Fingerprint enhancement. (a) **Left:** Original fingerprint image, $\Omega = (0, 256)^2$. (b) **Right:** Filtered with coherence-enhancing anisotropic diffusion, $\sigma = 0.5$, $\rho = 4$, $t = 20$.

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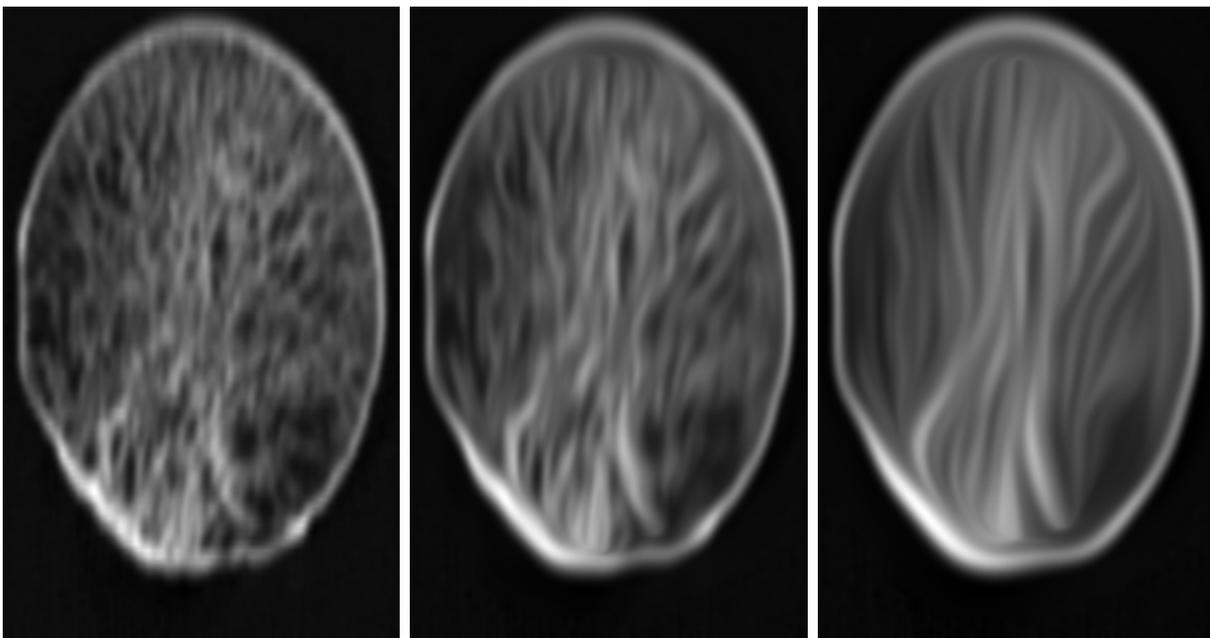
Coherence-Enhancing Anisotropic Diffusion (4)



Scale-space behaviour of coherence-enhancing diffusion ($\sigma = 0.5$, $\rho = 2$). (a) **Top left:** Original fabric image, $\Omega = (0, 257)^2$. (b) **Top right:** $t = 20$. (c) **Bottom left:** $t = 120$. (d) **Bottom right:** $t = 640$.

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Coherence-Enhancing Anisotropic Diffusion (5)



(a) **Left:** High resolution slipping CT scan of a femoral bone, $\Omega = (0, 186) \times (0, 300)$. (b) **Middle:** Filtered by coherence-enhancing anisotropic diffusion, $\sigma = 0.5$, $\rho = 6$, $t = 16$. (c) **Right:** Ditto with $t = 128$.

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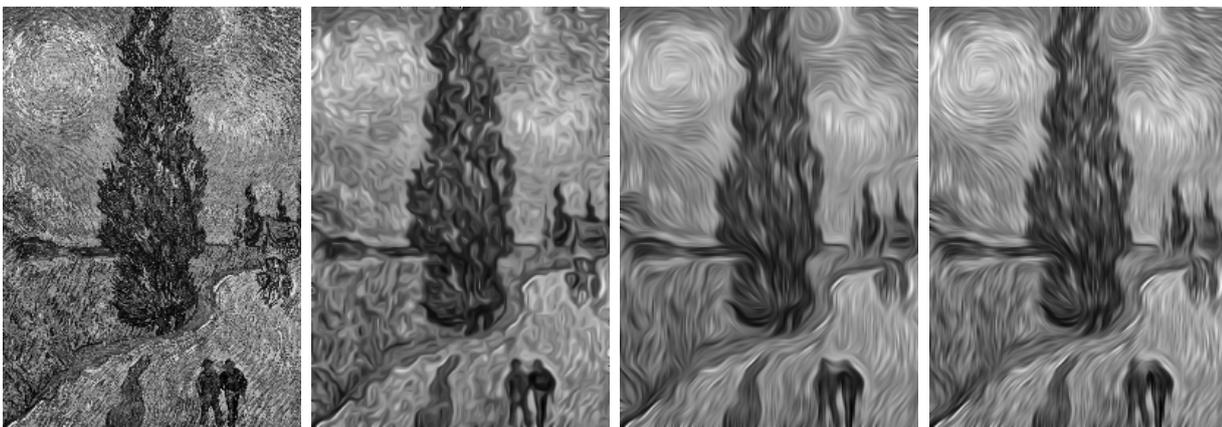
Coherence-Enhancing Anisotropic Diffusion (6)



Image restoration using coherence-enhancing anisotropic diffusion. (a) **Left:** "Selfportrait" by van Gogh (Saint-Rémy, 1889; Paris, Musée d'Orsay), $\Omega = (0, 215) \times (0, 275)$. (b) **Right:** Filtered, $\sigma = 0.5$, $\rho = 4$, $t = 6$.

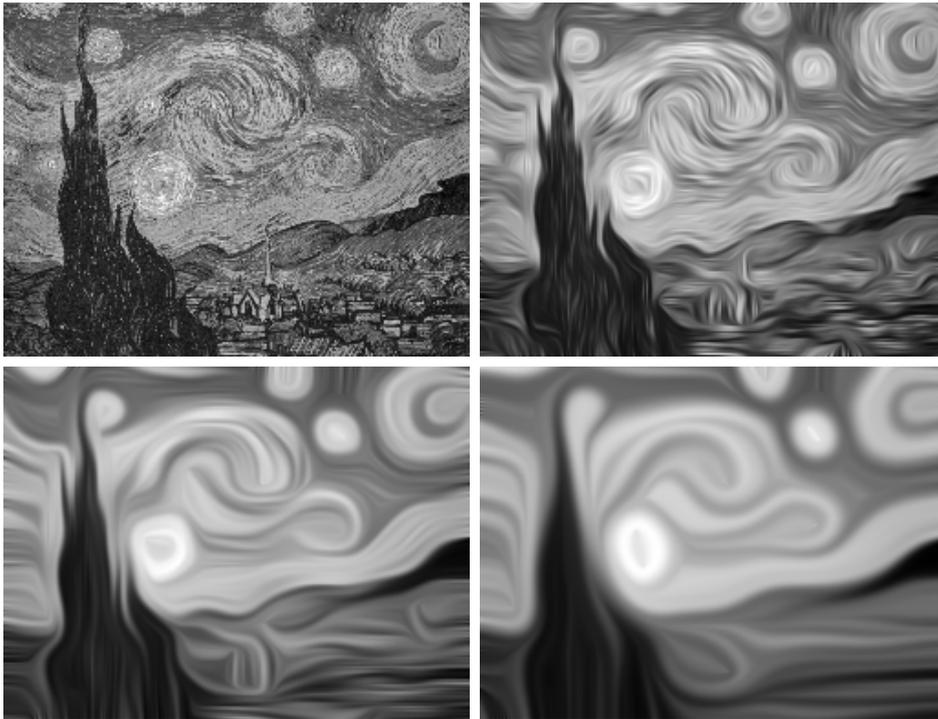
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Coherence-Enhancing Anisotropic Diffusion (7)



Impact of the integration scale on coherence-enhancing anisotropic diffusion ($\sigma = 0.5$, $t = 8$). (a) **Left:** "Lane under Cypresses below the Starry Sky" by van Gogh (Auvers-sur-Oise, 1890; Otterlo, Rijksmuseum Kröller-Müller), $\Omega = (0, 203) \times (0, 290)$. (b) **Middle left:** Filtered with $\rho = 1$. (c) **Middle right:** $\rho = 4$. (d) **Right:** $\rho = 6$.

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Scale-space properties of coherence-enhancing anisotropic diffusion ($\sigma = 0.5$, $\rho = 4$). (a) **Top left:** “Starry Night” by van Gogh (Saint-Rémy, 1889; New York, Museum of Modern Art), $\Omega = (0, 255) \times (0, 199)$. (b) **Top right:** $t = 8$. (c) **Bottom left:** $t = 64$. (d) **Bottom right:** $t = 512$.

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Summary

Summary

- ◆ Two anisotropic models:
 - Edge-enhancing diffusion (EED):
inhibits smoothing across edges, but not along them
 - Coherence-enhancing diffusion (CED):
basically a 1-D smoothing along flow-like structures
- ◆ Structure tensor:
 - generalises gradient
 - eigenvalues and eigenvectors:
for detecting corners and coherent structures
 - necessary for steering CED
- ◆ Anisotropic diffusion is applicable to
 - medical imaging
 - computer aided quality control

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(detailed explanation of the structure tensor)
- ◆ J. Weickert: Theoretical foundations of anisotropic diffusion in image processing. *Computing*, Supplement 11, 221–236, 1996. www.mia.uni-saarland.de/weickert/Papers/dag94.ps.gz
(introduced edge-enhancing anisotropic diffusion)
- ◆ J. Weickert: Coherence-enhancing diffusion filtering. *International Journal of Computer Vision*, Vol. 31, No. 2/3, 111–127, 1999. www.mia.uni-saarland.de/weickert/Papers/ced.ps.gz
(details on coherence-enhancing diffusion)
- ◆ J. Weickert, *Anisotropic Diffusion in Image Processing*, Teubner, Stuttgart, 1998.
(The structure tensor is sketched in Section 2.2, and EED and CED are investigated in Chapter 5.)
The book is based on a Ph.D. thesis which may be downloaded from
www.mia.uni-saarland.de/weickert/Papers/diss.ps.gz

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Assignment C2

Assignment C2 – Classroom Work

Problem 1 (Stencils and Discrete Diffusion Properties)

Investigate which of the following stencils satisfy the requirements (D1)–(D6) of a discrete diffusion process in the sense of Lecture 5. If some of these requirements are violated, which scale-space properties are no longer satisfied when the corresponding filter is applied iteratively?

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| (a) | $\begin{array}{ c c c } \hline 0 & \frac{1}{8} & 0 \\ \hline \frac{1}{8} & \frac{1}{4} & \frac{1}{8} \\ \hline 0 & \frac{3}{8} & 0 \\ \hline \end{array}$ | (b) | $\begin{array}{ c c c } \hline \frac{1}{7} & \frac{1}{7} & 0 \\ \hline \frac{1}{7} & \frac{1}{7} & \frac{1}{7} \\ \hline 0 & \frac{1}{7} & \frac{1}{7} \\ \hline \end{array}$ | (c) | $\begin{array}{ c c c } \hline 0 & \frac{1}{8} & 0 \\ \hline \frac{1}{8} & \frac{1}{8} & \frac{1}{8} \\ \hline 0 & \frac{1}{8} & 0 \\ \hline \end{array}$ | (d) | $\begin{array}{ c c c } \hline \frac{1}{8} & \frac{1}{8} & \frac{1}{8} \\ \hline \frac{1}{8} & \frac{1}{8} & \frac{1}{8} \\ \hline \frac{1}{8} & \frac{1}{8} & 0 \\ \hline \end{array}$ |
| (e) | $\begin{array}{ c c c } \hline 0 & \frac{1}{2} & 0 \\ \hline \frac{1}{2} & -1 & \frac{1}{2} \\ \hline 0 & \frac{1}{2} & 0 \\ \hline \end{array}$ | (f) | $\begin{array}{ c c c } \hline 0 & \frac{1}{4} & 0 \\ \hline \frac{1}{4} & 0 & \frac{1}{4} \\ \hline 0 & \frac{1}{4} & 0 \\ \hline \end{array}$ | (g) | $\begin{array}{ c c c } \hline \frac{1}{8} & 0 & \frac{1}{8} \\ \hline 0 & \frac{1}{2} & 0 \\ \hline \frac{1}{8} & 0 & \frac{1}{8} \\ \hline \end{array}$ | (h) | $\begin{array}{ c c c } \hline 0 & \frac{1}{4} & 0 \\ \hline 0 & \frac{1}{2} & 0 \\ \hline 0 & \frac{1}{4} & 0 \\ \hline \end{array}$ |

Problem 2 (AOS Scheme)

Show that the AOS scheme differs from the semi-implicit scheme by terms that are at least of quadratic order in the time step size.

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