

IMAGE PROCESSING AND COMPUTER VISION

ASSIGNMENT T1

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Group T1: Tue, 14-16 (Sebastian Zimmer)

1.1 Signal-to-Noise Ratio

a. Let's see, if $\text{SNR}(f, g) = 0$:

$$\begin{aligned}
 \text{SNR}(f, g) &= 0 \\
 10 \cdot \log_{10} \frac{\sigma^2(g)}{\sigma^2(n)} &= 0 \\
 \log_{10} \frac{\sigma^2(g)}{\sigma^2(n)} &= 0 \\
 \log_{10} \sigma^2(g) - \log_{10} \sigma^2(n) &= 0 \\
 \log_{10} \sigma^2(g) &= \log_{10} \sigma^2(n) \\
 \sigma^2(g) &= \sigma^2(n)
 \end{aligned}$$

So this is the case, if the noise doesn't affect the original image.

b. For the sake of readability, I define a function as follows:

$$short(x, y) = \sum_{i=1}^M \sum_{j=1}^N (x - y)^2$$

$$\begin{aligned}
 \text{SNR}(u, g) &= \text{SNR}(f, g) + 10\text{dB} \\
 \Leftrightarrow 10 \cdot \log_{10} \frac{\frac{1}{MN} \cdot short(g_{i,j}, \mu)}{\frac{1}{MN} \cdot short(u_{i,j}, g_{i,j})} &= 10 \cdot \log_{10} \frac{\frac{1}{MN} \cdot short(g_{i,j}, \mu)}{\frac{1}{MN} \cdot short(f_{i,j}, g_{i,j})} + 10 \\
 \Leftrightarrow \log_{10} \frac{short(g_{i,j}, \mu)}{short(u_{i,j}, g_{i,j})} & \\
 - \log_{10} \frac{short(g_{i,j}, \mu)}{short(f_{i,j}, g_{i,j})} &= 1 \\
 \Leftrightarrow \log_{10} \frac{\frac{\sum_{i=1}^M \sum_{j=1}^N (g_{i,j})^2}{\sum_{i=1}^M \sum_{j=1}^N (u_{i,j} - g_{i,j})^2}}{\frac{\sum_{i=1}^M \sum_{j=1}^N (g_{i,j})^2}{\sum_{i=1}^M \sum_{j=1}^N (f_{i,j} - g_{i,j})^2}} &= 1 \\
 \Leftrightarrow \log_{10} \frac{\sum_{i=1}^M \sum_{j=1}^N (f_{i,j} - g_{i,j})^2}{\sum_{i=1}^M \sum_{j=1}^N (u_{i,j} - g_{i,j})^2} &= 1 \\
 \Leftrightarrow \frac{\sum_{i=1}^M \sum_{j=1}^N (f_{i,j} - g_{i,j})^2}{\sum_{i=1}^M \sum_{j=1}^N (u_{i,j} - g_{i,j})^2} &= 10
 \end{aligned}$$

$$\begin{aligned}
&\Leftrightarrow \sum_{i=1}^M \sum_{j=1}^N (f_{i,j} - g_{i,j})^2 = 10 \cdot \sum_{i=1}^M \sum_{j=1}^N (u_{i,j} - g_{i,j})^2 \\
&\Leftrightarrow \frac{1}{MN} \cdot \sum_{i=1}^M \sum_{j=1}^N (f_{i,j} - g_{i,j})^2 = 10 \cdot \frac{1}{MN} \cdot \sum_{i=1}^M \sum_{j=1}^N (u_{i,j} - g_{i,j})^2 \\
&\Leftrightarrow \sigma^2(n) = 10 \cdot \sigma^2(n')
\end{aligned}$$

where $\sigma^2(n')$ is the noise variance of the filtered image.

Interpretation:

As one can see, playing with the SNR can have a huge impact on the noise variance. The noise variance of the filtered image is 10 times higher than the noise variance of the original image.

- c. • If the initial image is constant, the variance is also constant. For example:

$$\begin{aligned}
g = 5 \Rightarrow \sigma^2(g) &= \frac{1}{MN} \sum_{i=1}^M \sum_{j=1}^N (g_{i,j} - \mu)^2 \\
\stackrel{\mu=0}{\Leftrightarrow} \sigma^2(g) &= \frac{1}{MN} \cdot 25 \cdot M \cdot N \\
\sigma^2(g) &= 25 = 5^2 = g^2
\end{aligned}$$

This means that the resulting image is the noise function with some additional weighting which is the constant image.

- Let's try to calculate $\text{SNR}(g, g)$:

$$\text{SNR}(g, g) = 10 \cdot \log_{10} \frac{\frac{1}{MN} \cdot \sum_{i=1}^M \sum_{j=1}^N (g_{i,j} - \mu)^2}{\underbrace{\frac{1}{MN} \cdot \sum_{i=1}^M \sum_{j=1}^N (g_{i,j} - g_{i,j})^2}_{=0}}$$

One cannot calculate this, because of the division by 0.

Since this SNR is not defined, one can interpret the result as follows:

Measuring how much your original image is deteriorated in comparison to your original image doesn't make sense, because you compare an image with itself.

1.2 Discrete vs. Continuous Convolution

a.

$$f_i = \begin{cases} \frac{1}{2} & (i \in \{0, 1\}) \\ 0 & (\text{else}) \end{cases}$$

$$\begin{aligned} (f * f)_k &= \sum_i f_{k-i} \cdot f_i = \sum_{i=0}^1 f_{k-i} \cdot f_i \\ &= \frac{1}{2} \cdot \sum_{i=0}^1 f_{k-i} = \frac{1}{2} \cdot (f_k + f_{k-1}) = g \end{aligned}$$

$$\begin{aligned} (g * f)_k &= \sum_i g_{k-i} \cdot f_i = \sum_{i=0}^1 g_{k-i} \cdot f_i \\ &= \frac{1}{2} \cdot \sum_{i=0}^1 g_{k-i} = \frac{1}{2} \cdot \sum_{i=0}^1 \left(\frac{1}{2} \cdot (f_k + f_{k-1}) \right)_{k-i} \\ &= \frac{1}{4} \cdot ((f_k + f_{k-1}) + (f_{k-1} + f_{k-2})) = h \end{aligned}$$

$$\begin{aligned} (h * f)_k &= \sum_i h_{k-i} \cdot f_i = \sum_{i=0}^1 h_{k-i} \cdot f_i \\ &= \frac{1}{2} \sum_{i=0}^1 h_{k-i} = \frac{1}{2} \cdot \frac{1}{4} \cdot \sum_{i=0}^1 ((f_k + f_{k-1}) + (f_{k-1} + f_{k-2}))_{k-i} \\ &= \frac{1}{8} [((f_k + f_{k-1}) + (f_{k-1} + f_{k-2})) + ((f_{k-1} + f_{k-2}) + (f_{k-2} + f_{k-3}))] \\ &= \frac{1}{8} ((f_k + f_{k-1}) + 2 \cdot (f_{k-1} + f_{k-2}) + (f_{k-2} + f_{k-3})) = l \end{aligned}$$

$$\begin{aligned} (l * f)_k &= \sum_i l_{k-i} \cdot f_i = \frac{1}{2} \cdot \sum_{i=0}^1 l_{k-i} \\ &= \frac{1}{2} \cdot \frac{1}{8} \cdot \sum_{i=0}^1 ((f_k + f_{k-1}) + 2 \cdot (f_{k-1} + f_{k-2}) + (f_{k-2} + f_{k-3}))_{k-i} \\ &= \frac{1}{16} \cdot [(f_k + f_{k-1}) + 2 \cdot (f_{k-1} + f_{k-2}) + (f_{k-2} + f_{k-3}) \\ &\quad + (f_{k-1} + f_{k-2}) + 2 \cdot (f_{k-2} + f_{k-3}) + (f_{k-3} + f_{k-4})] \\ &= \frac{1}{16} \cdot [(f_k + f_{k-1}) + 3 \cdot (f_{k-1} + f_{k-2}) \\ &\quad + 3 \cdot (f_{k-2} + f_{k-3}) + (f_{k-3} + f_{k-4})] \end{aligned}$$

- b. For this exercise, I have a strong evidence that my solution is not correct. Nevertheless I want to put it here because of a small chance that it's right anyway ;-)

$$\begin{aligned}
 (f * f)(x) &= \int_{-\infty}^{\infty} f(x-y) \cdot f(y) dy \\
 &= \int_{-\infty}^{-2} f(x-y) \cdot f(y) dy + \int_{-2}^0 f(x-y) \cdot f(y) dy \\
 &\quad + \int_0^2 f(x-y) \cdot f(y) dy + \int_2^{\infty} f(x-y) \cdot f(y) dy \\
 &= \int_{-2}^0 f(x-y) \cdot f(y) dy + \int_0^2 f(x-y) \cdot f(y) dy \\
 &= \int_{-2}^{-1} f(x-y) \cdot f(y) dy + \int_{-1}^1 f(x-y) \cdot f(y) dy + \int_1^2 f(x-y) \cdot f(y) dy \\
 &= \int_{-1}^1 f(x-y) \cdot f(y) dy = \frac{1}{2} \cdot \int_{-1}^1 f(x-y) dy \\
 &= \frac{1}{2} \cdot \int_{x-1}^{x+1} \frac{1}{2} dy = \frac{1}{2} \cdot \left[\frac{1}{2} y \right]_{x-1}^{x+1} \\
 &= \frac{1}{2} \cdot \left(\frac{1}{2} \cdot (x+1) - \frac{1}{2} \cdot (x-1) \right) \\
 &= \frac{1}{2} \cdot \left(\frac{1}{2} x + \frac{1}{2} - \frac{1}{2} x + \frac{1}{2} \right) \\
 &= \frac{1}{2}
 \end{aligned}$$

This result is why I'm not sure whether it is right or wrong. If you would repeat this convolution step 3 times as the exercise requests it you would get the same result again.

1.3 Properties of the Discrete Convolution

a. To show: $(\alpha \cdot f + \beta \cdot g) * w = \alpha \cdot (f * w) + \beta \cdot (g * w) \quad \forall \alpha, \beta \in \mathbb{R}$

$$\begin{aligned}
 ((\alpha \cdot f + \beta \cdot g) * w)_i &= \sum_{k=-\infty}^{\infty} (\alpha \cdot f + \beta \cdot g)_{i-k} \cdot w_k \\
 &= \sum_{k=-\infty}^{\infty} (\alpha \cdot f \cdot w_{2k-i} + \beta \cdot g \cdot w_{2k-i})_{i-k} \\
 &= \sum_{k=-\infty}^{\infty} ((\alpha \cdot f \cdot w_{2k-i})_{i-k} + (\beta \cdot g \cdot w_{2k-i})_{i-k}) \\
 &= \sum_{k=-\infty}^{\infty} (\alpha \cdot (f \cdot w_{2k-i})_{i-k} + \beta \cdot (g \cdot w_{2k-i})_{i-k}) \\
 &= \sum_{k=-\infty}^{\infty} \alpha \cdot (f \cdot w_{2k-i})_{i-k} + \sum_{k=-\infty}^{\infty} \beta \cdot (g \cdot w_{2k-i})_{i-k} \\
 &= \alpha \cdot \sum_{k=-\infty}^{\infty} f_{i-k} \cdot w_k + \beta \cdot \sum_{k=-\infty}^{\infty} g_{i-k} \cdot w_k \\
 &= \alpha \cdot (f * w)_i + \beta \cdot (g * w)_i
 \end{aligned}$$

b. To show: $f * w = w * f$

$$\begin{aligned}
 (f * w)_i &= \sum_{k=-\infty}^{\infty} f_{i-k} \cdot w_k = \sum_{k=-\infty}^{\infty} w_k \cdot f_{i-k} \\
 &= \sum_{k=-\infty}^{\infty} w_{k-i} \cdot f_{-k} = \sum_{k=-\infty}^{\infty} w_{i-k} \cdot f_k \\
 &\stackrel{(*)}{=} \sum_{k=-\infty}^{\infty} w_{i-k} \cdot f_k \\
 &= (w * f)_i
 \end{aligned}$$

where (*) is because of the symmetry of the sum.

c. Claim:

$$e = \begin{cases} 1 & x = 0 \\ 0 & x \neq 0 \end{cases}$$

Proof:

$$(f * e)_i = \sum_{k=-\infty}^{\infty} f_{i-k} \cdot e_k = \underbrace{\sum_{k=-\infty}^{-1} f_{i-k} \cdot e_k}_{=0} + f_i \cdot 1 + \underbrace{\sum_{k=1}^{\infty} f_{i-k} \cdot e_k}_{=0} = f_i$$

1.4 Continuous Fourier Transform

a. We have the 1-D hat function:

$$f(x) = \begin{cases} \frac{2-|x|}{4} & (-2 \leq x \leq 2) \\ 0 & (\text{else}) \end{cases}$$

To make life easier, I re-define the function f as follows:

$$f(x) = \begin{cases} \frac{2+x}{4} & (-2 \leq x < 0) \\ \frac{2-x}{4} & (0 \leq x \leq 2) \\ 0 & (\text{else}) \end{cases}$$

Let's compute the Fourier transform:

$$\begin{aligned} \hat{f}(u) &= \mathcal{F}[f](u) = \int_{-\infty}^{\infty} f(x) \cdot e^{-i2\pi ux} dx \\ &= \int_{-2}^2 f(x) \cdot e^{-i2\pi ux} dx \\ &= \int_{-2}^0 f(x) \cdot e^{-i2\pi ux} dx + \int_0^2 f(x) \cdot e^{-i2\pi ux} dx \\ &= \int_{-2}^0 \frac{2+x}{4} \cdot e^{-i2\pi ux} dx + \int_0^2 \frac{2-x}{4} \cdot e^{-i2\pi ux} dx \\ &= \left[\frac{2+x}{4} \cdot \left(-\frac{1}{i2\pi u} \right) \cdot e^{-i2\pi ux} \right]_{-2}^0 - \int_{-2}^0 \frac{1}{4} \cdot \left(-\frac{1}{i2\pi u} \right) \cdot e^{-i2\pi ux} dx \\ &\quad + \left[\frac{2-x}{4} \cdot \left(-\frac{1}{i2\pi u} \right) \cdot e^{-i2\pi ux} \right]_0^2 - \int_0^2 \left(-\frac{1}{4} \right) \cdot \left(-\frac{1}{i2\pi u} \right) \cdot e^{-i2\pi ux} dx \\ &= \frac{1}{2} \cdot \left(-\frac{1}{i2\pi u} \right) \cdot e^0 - \frac{1}{4} \cdot \left(-\frac{1}{i2\pi u} \right) \cdot \left[-\frac{1}{i2\pi u} \cdot e^{-i2\pi ux} \right]_{-2}^0 \\ &\quad + \left(0 - \frac{1}{2} \cdot \left(-\frac{1}{i2\pi u} \right) \cdot e^0 \right) - \left(-\frac{1}{4} \right) \cdot \left(-\frac{1}{i2\pi u} \right) \cdot \left[-\frac{1}{i2\pi u} \cdot e^{-i2\pi ux} \right]_0^2 \end{aligned}$$

$$\begin{aligned}
&= \frac{1}{2} \cdot \left(-\frac{1}{i2\pi u} \right) - \frac{1}{4} \cdot \left(-\frac{1}{i2\pi u} \right) \cdot \left[\left(-\frac{1}{i2\pi u} \right) - \left(-\frac{1}{i2\pi u} \right) \cdot e^{-i2\pi u(-2)} \right] \\
&\quad - \frac{1}{2} \cdot \left(-\frac{1}{i2\pi u} \right) - \left(-\frac{1}{4} \right) \cdot \left(-\frac{1}{-i2\pi u} \right) \cdot \left[-\frac{1}{i2\pi u} \cdot e^{-i2\pi u \cdot 2} - \left(-\frac{1}{i2\pi u} \right) \right] \\
&= -\frac{1}{2} \cdot \frac{1}{i2\pi u} - \frac{1}{4} \cdot \left(\frac{1}{i2\pi u} \right)^2 - \frac{1}{4} \cdot \left(\frac{1}{i2\pi u} \right)^2 \cdot e^{-i2\pi u \cdot (-2)} \\
&\quad + \frac{1}{2} \cdot \frac{1}{i2\pi u} + \frac{1}{4} \cdot \left(\frac{1}{i2\pi u} \right)^2 \cdot e^{-i2\pi u \cdot 2} - \frac{1}{4} \cdot \left(\frac{1}{i2\pi u} \right)^2 \\
&= -\frac{1}{2} \cdot \left(\frac{1}{i2\pi u} \right)^2 + \frac{1}{4} \cdot \left(\frac{1}{i2\pi u} \right)^2 \cdot (e^{-i2\pi u \cdot 2} - e^{i2\pi u \cdot 2}) \\
&= -\frac{1}{2} \cdot \frac{1}{i^2 4\pi^2 u^2} + \frac{1}{4} \cdot \frac{1}{i^2 4\pi^2 u^2} \cdot e^4 (e^{-i\pi u} - e^{i\pi u}) \\
&= -\frac{1}{2} \cdot \frac{1}{i^2 4\pi^2 u^2} + \frac{1}{4} \cdot \frac{1}{i^2 4\pi^2 u^2} \cdot e^4 \cdot (-2i \sin(\pi u)) \\
&= -\frac{1}{2} \cdot \frac{1}{i^2 4\pi^2 u^2} + \frac{1}{4} \cdot \frac{1}{-i2\pi^2 u^2} \cdot e^4 \cdot \sin(\pi u) \\
&= \frac{1}{8i^2 \pi^2 u^2} - \frac{e^4 \cdot \sin(\pi u)}{8i\pi^2 u^2} \\
&= \frac{-1 - e^4 \cdot \sin(\pi u) \cdot i}{8i^2 \pi^2 u^2} \\
&= -\frac{1}{8i^2 \pi^2 u^2} \cdot (1 + e^4 \cdot \sin(\pi u) \cdot i) \\
&\stackrel{i^2=-1}{=} \frac{1}{8\pi^2 u^2} \cdot (1 + e^4 \cdot \sin(\pi u) \cdot i)
\end{aligned}$$

b.

$$\begin{aligned}
|\hat{f}(u)| &= \left| \frac{1}{8\pi^2 u^2} \right| \cdot |1 + e^4 \cdot \sin(\pi u) \cdot i| \\
&= \frac{1}{8\pi^2 u^2} + \left| \frac{e^4 \cdot \sin(\pi u) \cdot i}{8\pi^2 u^2} \right| \\
&= \frac{1}{8\pi^2 u^2} + \left| \frac{e^4 \cdot i}{8\pi u} \right| \cdot \left| \frac{\sin(\pi u)}{\pi u} \right| \\
&= \frac{1}{8\pi^2 u^2} + \left| \frac{e^4 \cdot i}{8\pi u} \right| \cdot |\operatorname{sinc}(\pi u)|
\end{aligned}$$