

Introduction to Stateflow, Part II

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The aim of this exercise set is, first, to introduce slightly more elaborate and concise STATEFLOW constructs such that work on the ignition control project will be more efficient. Furthermore, it will provide some insight into sensing and measuring environment entities with polling real-time systems.

Exercise 1: State actions

As self loops — i.e. transitions with coinciding source and target state — are extremely frequent in everyday STATEFLOW models, there is special syntax for avoiding¹ these. States can be equipped with so-called *state actions*. Such actions are, depending on their specific type, executed upon entering the state, upon exiting the state, or when staying in a state because no outgoing transition fires. The latter form of state action constitutes a replacement for self loops that is both more concise and more efficient upon simulation than a self loop.

There are two forms of such state actions that are executed when staying in a state, i.e. when the state chart is triggered, yet no outgoing transition fires:

1. A *during* action, which is executed upon *every activation* (i.e. triggering) of the state chart unless some transition originating in the state fires, has the syntax

`during: action`

where the syntax of actions is as for the action part of a transition. Such an action is (almost¹) equivalent to a self-loop transition labelled with empty guard (i.e., guard `[true]`) and action part *action*.

2. An *event-triggered action* executed upon *every occurrence of the respective event* unless some transition originating in the state fires:

`on event: action`

Such an action is (almost¹) equivalent to a self-loop transition labelled with guard *event* and action part *action*.

¹In fact, you may consider the new notation introduced here as merely being an abbreviation. Yet, there are notable semantic differences: First, the *during* and *on* state actions introduced herein do always have lower priority than all transitions originating from the respective state. Second, state actions are — in contrast to outgoing transitions, including self-loops — not considered to actually leave the state, which is providing a visible difference in the interaction with “temporal logic events”, cf. exercise 2.

For associating such actions to a state, you have to extend the state name with a slash ("/") and to add additional lines with `during` or `on` actions to the state name: e.g. extended state name

```
Adams_adventurous_state/  
on God_speaking: utter_wish_for_Eve  
on Eve_whispering: eaten_apples++
```

defines the state name to be "Adams_adventurous_state" and associates two state actions to that state. These state actions are "utter_wish_for_Eve", to be issued upon event "God_speaking", and increment of variable `eaten_apples` whenever Eve is whispering (and no outgoing transition saves Adam...).

Exercise: Simplify your most advanced stop-watch from the last exercise set by use of state actions.

Exercise 2: "Temporal logic events"

A further frequently encountered operation is counting event occurrences in order to perform a certain action only if a certain number of event occurrences has happened, e.g. in dividing frequencies. STATEFLOW offers so-called *temporal logic events* for this purpose (thereby actually abusing the term "temporal logic"). You may use

```
after(number, event)
```

as an event in the trigger condition of a transition, where *number* is a natural number (or an expression evaluating to such) and *event* is an event name. The semantics is that the corresponding transition will be enabled iff at least *number* instances of *event* have occurred since entering the transition source state and the remaining part of the trigger condition is true. E.g. a transition with label

```
after(4, Calls_from_God) / march
```

will be enabled after seeing four `Calls_from_God`, yet only if the chart was *stably* in the source state of the transition during those four calls.²

Exercise: Simplify your most advanced stop-watch from the last exercise set by use of `after` events.

Exercise 3: Measuring frequencies

Measuring frequencies is one of the most fundamental operations in embedded control, as a variety of physical quantities is in practice measured via measuring a frequency related to the quantity, e.g. speeds are often measured by measuring the frequency of a signal originating from a rotation sensor. Basically, there are two methods for measuring frequencies (mixtures and more advanced schemes are obviously possible) of digital signals:

²Note that it is here where `during` or `on` actions behave notably different from self-loops: self-loops leave a state (thus resetting the "count" underlying the `after` event) while `during` or `on` actions don't leave the state.

1. to count the number of edges over a time window of fixed length;
2. to measure the time lack between two (or more generally n , with $n \geq 2$) successive edges.

These two methods have their specific pros and cons. In implementations polling their inputs at regular time intervals those two techniques do, in particular, yield measurements which reach their maximum imprecision at different ends of the frequency scale.

Exercise: Use the matlab model “`frequencycount.mdl`”. This model contains

1. a frequency generator that can be set to any frequency between 1Hz and 500Hz by moving a slider called “Frequency” (double-left-click on the block named “Frequency” to gain access to the slider);
2. an empty STATEFLOW state chart called “Frequency counter”, which has
 - an output to Simulink called “Measurement”, via which the chart shall deliver the measured value for the frequency,
 - an input from Simulink called “Signal” that feeds the signal from the frequency generator into the chart,
 - a trigger input “clk” driving the chart via a positively edge-triggered signal of 1kHz frequency (i.e., the chart performs a step every ms);
3. an oscilloscope “Freq” which displays both the actual and the measured (i.e., output by the STATEFLOW chart) frequency.

Implement both forms of frequency measurement by filling in the STATEFLOW chart and compare the properties of the two approaches. What is a reasonable magnitude for the width of the time window when using technique 1?

